

REVISION HISTORY

REV	EDITOR	REVISION DESCRIPTION	CARD ENGINE REV	APPROVAL	DATE
1	Erik Reynolds	Beta	-	ER	5/28/04
Α	James Wicks	Removed Preliminary References	201	ER	8/19/04
В	James Wicks	Updated Pin Descriptions	А	ER	1/13/05
С	James Wicks / Mike Aanenson	Connector Pin Descriptions: - J1A pin 6 LCD_VEEEN - J1B pin 11 PCC_nCE1B - J1B pin 12 PCC_nCE2B - J1B pin 18 PCC_nCD2 - J1B pin 19 PCC_nCD1 J1C multiplex table, Section 5.5.1: - Removed Pins 17 and 18 - Pin 23 uP_IRQD corrected to INT4, PF4 J1A multiplex table, Section 5.5.2: - Pin 7 changed to pin 6 LCD_VEEEN - Added Pins 17 and 18, uP_STATUS1 and uP_STATUS2 - Added Pin 62, uP_PCC_RDYA J1B multiplex table, Section 5.5.3: - Pin 13 uP_PCC_nIOIS16 corrected to PA2 - Pin 14 uP_PCC_RDYB corrected to PF7 - Pin 15 uP_PCC_nVAIT corrected Alternate Description - Removed Pins 16, 17, 18, and 19 - Pin 47 uP_UARTC_RX pin number corrected. -Revision History Table corrected. Rev A was for Card Engine Rev 201. Rev B was for Card Engine Rev A.	В	MAA	3/18/05
D	Chris Rempel	Updated Section 5: Pin Descriptions & Functions	В	HAR	5/6/05

REV	EDITOR	REVISION DESCRIPTION	SCHEMATIC PN & REV	APPROVAL	DATE
Е	Jed Anderson	 Revision History Table: Replaced "Card Engine Rev" category with "Schematic PN & Rev" Removed Section 1.4 "Card Engine Advantages" Sections 1.6.1 and 1.6.1.1: Updated tables Section 1.6.1.1: Added power supply note Section 2.1.2: Updated LH7A404 MCU Block Diagram Section 2.7: Updated link to Intel website Section 5.1: Changed J1C pin #22 nCHRDY to Input Section 5.1: Fixed description of pin #26 uP_TEST2 signal for proper JTAG use Section 5.2: Corrected J1A pin #11 LCD_VSYNC – LCD_SPS description Section 6.1: Updated Hirose connector PN after previous PN was discontinued Section 6.1: Added Important note General formatting and grammatical changes throughout 	80000258 Rev C	MAA	05/04/07
F	Jed Anderson	Updated Product Brief Sections 1.3, 2.13, & 3.5.2: Removed references to the Altera CPLD and added references to the Xilinx CPLD Removed references to the IDK kit throughout General formatting and grammatical changes throughout	80000258 Rev C	JCA	06/27/07

Please check www.logicpd.com for the latest revision of this hardware specification, product change notifications, and additional application notes.

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PRODUCT BRIEF:

Logic :: Sharp

LH7A404 CARD ENGINE System on Module

The LH7A404 Card Engine is a compact, product-ready hardware and software solution that fast forwards your embedded product design.

The LH7A404 Card Engine is a complete System on Module (SOM) that offers essential features for handheld and embedded networking applications. Use of custom baseboards makes the Card Engine the ideal foundation for OEMs developing handheld and compact products. The Card Engine provides a common reference pin-out on its expansion connectors, which enables easy scalability to next generation microprocessor Card Engines when new functionality or performance is required.

Application development is performed right on the product-ready LH7A404 Card Engine and software Board Support Packages (BSPs), which enables you to seamlessly transfer your application code and hardware into production.

The LH7A404 Card Engine is ideal for applications in the medical, point-of-sale, industrial, and security markets. From patient



LH7A404 CARD ENGINE

monitoring and medical imaging, to card payment terminals and bar code readers, to CCTV cameras and intruder alarms, the LH7A404 Card Engine allows for powerful versatility and long-life products.

LH7A404 CARD ENGINE :: HIGHLIGHTS:

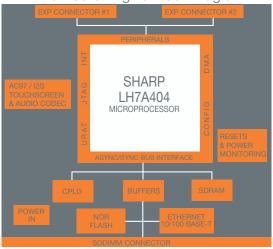
- + Product-ready System on Module with the Sharp LH7A404 microprocessor running up to 200 MHz
- +Compact form factor 60.2 mm x 67.8 mm x 4.4 mm
- +Long product life-cycle
- +0 °C to 70 °C (commercial temp) or -40 °C to 85 °C (industrial temp)
- +RoHS compliant

LH7A404 ZOOM™ SDK :: FEATURES:

- +Application baseboard
- +LH7A404 Card Engine (CENGLH7A404-11-503HCR)
- + Necessary accessories to immediately get up and running
- +Kit available from Logic (SDK-LH7A404-11-6416R)
- +See Zoom™ SDK product brief for more information



LH7A404 Card Engine Block Diagram



LH7A404 Card Engine Ordering Information

	Speed (MHz)		NAND Flash (MB)			Audio	Ethernet	Temp (°C)
CENGLH7A404-11-503HC ¹	200	64	0	16	Υ	Υ	Υ	0 – 70
CENGLH7A404-11-503HCR	200	64	0	16	Υ	Υ	Υ	0 – 70
CENGLH7A404-11-504HCR	200	64	0	32	Υ	Υ	Υ	0 – 70
CENGLH7A404-11-504HIR	200	64	0	32	Υ	Υ	Υ	-40 – 85

^{1.} This non-RoHS configuration is only available as part of the LH7A404 Zoom SDK. For production volumes, please use the RoHS compliant configuration.

LH7A404 ZOOM™ SDK Ordering Information

Logic Model Number	SOM Configuration	Recommended Resale
SDK-LH7A404-11-6416 ¹	CENGLH7A404-11-504HC ¹	\$399
SDK-LH7A404-11-6416R	CENGLH7A404-11-504HCR	\$399

1. This is a non-RoHS configuration.

LOGIC

LOGIC WEBSITE :: DESIGN RESOURCES:

- +Logic Technical Support : http://www.logicpd.com/support/
- +Technical Discussion Group: http://www.logicpd.com/support/tdg/
- +Frequently Asked Questions (FAQ): http://www.logicpd.com/support/faq/
- +For more information contact Logic Sales : product.sales@logicpd.com



embedded product solutions

411 N. Washington Ave. Suite 400 Minneapolis, MN 55401 T: 612.672.9495 F: 612.672.9489 I: www.logicpd.com

Product Features

Processor

+Sharp ARM 922TDMI LH7A404 microprocessor running up to 200 MHz

SDRAM Memory

+64 MB SDRAM standard

Flash Memory

+16 or 32 MB NOR

Display

- +Programmable color LCD controller
- +Built-in driver supports up to 1024x768 with 8-bit LCD interface

Touch Screen

+Integrated 4-wire touch screen controller

Network Support

+10/100 Base-T Ethernet controller for application/debug (SMSC LAN 91C111)

Audio

+AC97audio codec

PC Card Expansion

- +CompactFlash Type I card (memory-mapped mode only)
- +Smart Card, MMC/SD, dual PCMCIA interfaces

USE

- +Two USB 2.0 full-speed host interfaces
- +One USB 2.0 full-speed device interface

Serial Ports

+Three 16C550 compatible UARTs

SSP

+Supports Motorola SPI, National Semiconductor MICROWIRE, TI SSI

GPIO

+Programmable I/O depending on peripheral requirements

Software

- +LogicLoader[™] (bootloader/monitor)
- +Windows CE 5.0 BSP

Mechanical

+60.2 mm wide x 67.8 mm long x 4.4 mm high

RoHS Compliant

PN: 1000571 Rev D

1.2 Acronyms

ACI Audio CODEC Interface
ADC Analog to Digital Converter
AFE Analog Front End Interface
AHB Advanced Hardware Bus
BSP Board Support Package

CPLD Complex Programmable Logic Device

DAC Digital to Analog Converter

DC Direct Current

DMA Direct Memory Access

DRAM Dynamic Random Access Memory

ENDEC Encoder Decoder
ESD Electro Static Dissipative
FET Field Effect Transistor
FIQ Fast Interrupt Request
FIFO First In First Out

GPIO General Purpose Input Output HAL Hardware Abstraction Laver

IC Integrated Circuit
I2S Inter-IC Sound
I/O Input/Output
IRQ Interrupt Request
LCD Liquid Crystal Display

LOLO LogicLoader™ MMC Multi Media Card NC No Connect PHY Physical Layer PLL Phase Lock Loop

PMOS P Metal Oxide Semiconductor

RTC Real Time Clock

SDK Starter Development Kit

SDRAM Synchronous Dynamic Random Access Memory

SIR Serial Infrared
SoC System on Chip
SOM System on Module
SSP Synchronous Serial Port

SPI Standard Programming Interface

TSC Touch Screen Controller
TTL Transistor-Transistor Logic

UART Universal Asynchronous Receive Transmit

UHCI Universal Host Controller Interface
VIC Vectored Interrupt Controller

1.3 Technical Specification

Please refer to the following component specifications and data sheets.

LH7A404-11 Card Engine IO Controller Interface Specification

LogicLoaderTM User's Manual

LH7A404 Universal Microcontroller User's Guide

Xilinx Coolrunner™-II CPLD Product Specification (XC2C128-7VQG100C)

Xilinx Device Package User Guide

Wolfson WM9708 AC97 Audio CODEC data sheet

1.4 Card Engine Interface

Logic's common Card Engine interface allows for easy migration to new processors and technology. Logic is constantly researching and developing new technologies to improve performance, lower cost, and increase feature capabilities. By using the common Card Engine footprint, it is possible to take advantage of Logic's work without having to re-spin the old design. Contact Logic sales for more information.

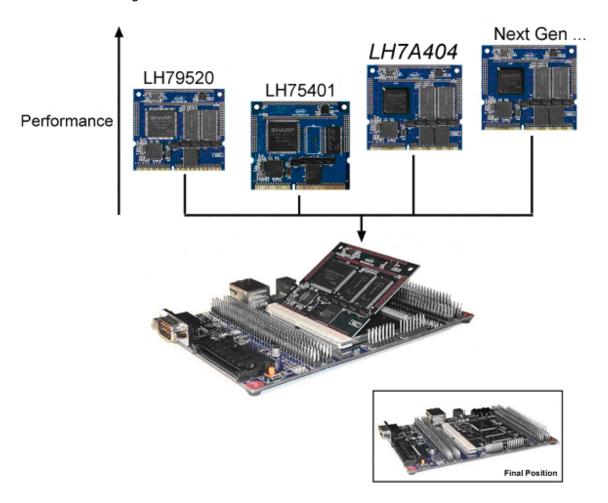


Figure 1.1: Card Engine Advantages

In fact, encapsulating a significant amount of your design onto the Card Engine reduces any long-term risk of obsolescence. If a component on the Card Engine design becomes obsolete, Logic will simply design for alternative part that is transparent to your product. Furthermore, Logic tests all Card Engines prior to delivery, decreasing time-to-market and ensuring a simpler and less costly manufacturing process.

1.5 LH7A404-11 Card Engine Block Diagram

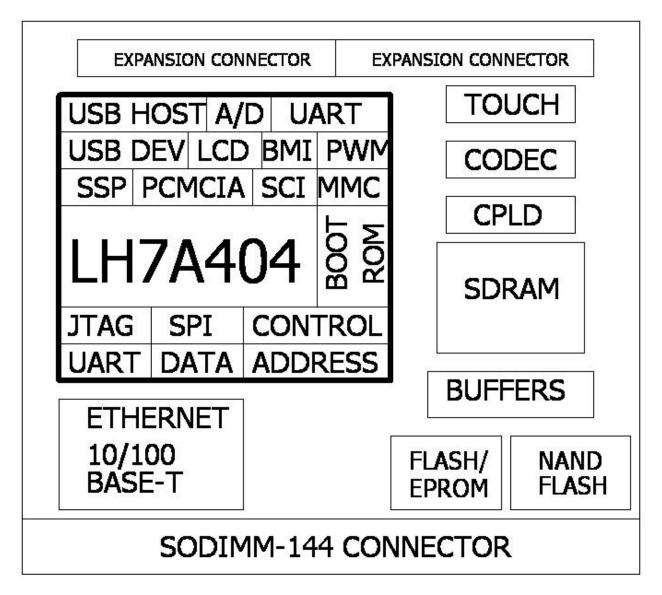


Figure 1.2: LH7A404-11 Card Engine Block Diagram

1.6 Electrical, Mechanical, and Environmental Specifications

1.6.1 Absolute Maximum Ratings

Parameter	Symbol	Rating	Unit
DC IO and Peripheral Supply Voltage	3.3V	-0.3 to 4.6	V
DC uP and SDRAM Supply Voltage	3.3V_uP_SDRAM	-0.3 to 4.6	V
DC Core Supply Voltage	VCORE	-0.3 to 2.4	V

NOTE: These stress ratings are only for transient conditions. Operation at or beyond absolute maximum rating conditions may affect reliability and cause permanent damage to the Card Engine and its components.

1.6.1.1 Recommended Operating Conditions

Parameter	Min	Typical	Max	Unit	Notes
DC IO & Peripheral Supply Voltage	3.0	3.3	3.6	V	1
DC IO Supply Active Current	_	196	286	mA	2
DC uP IO and SDRAM Supply Voltage	3.0	3.3	3.6	V	
DC uP IO and SDRAM Supply Current	_	48	66	mA	
DC Core Supply Voltage	1.71	1.8	1.89	V	1
DC Core Supply Active Current	_	126	222	mA	2
Commercial Operating Temperature	0	25	70	°C	
Industrial Operating Temperature	-40	25	85	°C	3
Storage Temperature	-40	25	85	°C	
Dimensions	_	2.35 x 2.6	_	Inches	
Weight	_	17	_	Grams	4
Connector Insertion/Removal	_	50	_	Cycles	
Input Signal High Voltage	_	2.0	_	V	
Input Signal Low Voltage	_	0.8	_	V	
Output Signal High Voltage	2.6	_	VIO	V	
Output Signal Low Voltage	GND	_	0.4	V	
Processor Core Crystal Frequency Tolerance	14744.8627	14745.6000	14746.3373	kHz	5,6,7
Processor RTC Crystal Frequency Tolerance	32.7670	32.7680	32.7690	kHz	5,8

NOTES:

- 1. Core voltage must never exceed IO and peripheral supply voltage.
- 2. This test was performed with the 91C111 chip power disabled.
- 3. Contact Logic for more information on an industrial temperature LH7A404-11 Card Engine
- 4. May vary depending on Card Engine configuration.
- 5. Min and Max values are based on the Min and Max tolerance of the processor datasheet.

- 6. The Min and Max values shown include the variation in frequency including the tolerance at 25 °C and the stability variation over temperature.
- 7. Core crystal tolerance requirement of processor is ±50 ppm.
- 8. RTC crystal tolerance requirement of processor is ±30 ppm.

NOTE: Sharp recommends that the 1.8V power supply be energized before the 3.3V supply. If this is not possible, the 1.8V supply may not lag the 3.3V supply by more than 100 microseconds. If longer delay time is needed, it is recommended that the voltage difference between the two power supplies be within 1.5V during power supply ramp up.

2 Electrical Specification

2.1 Microcontroller

2.1.1 LH7A404 Microcontroller

The LH7A404-11 Card Engine uses Sharp's highly integrated system on a chip LH7A404 microcontroller. This SoC possesses a 32-bit ARM922T RISC core and provides many integrated on-chip peripherals including:

Integrated ARM922T™ Core

- □ 32-bit ARM922TTM RISC Core
- □ 16kB Cache: 8kB Instruction Cache and 8kB Data Cache
- □ MMU
- □ 4 GB logical address space

80 KB on-chip SRAM Integrated LCD Controller

- □ Up to 800 x 600 Resolution at 16-bit color
 - o (1024 x 786 at 8 bits color)
- □ Supports STN, TFT, and HR-TFT
- □ Up to 65,536 Colors

Three UARTs
Classic IrDA (up to 115.2 Kbps)
SSP interface
AC97 CODEC Interface
1 USB Client and 1 USB host Interface (USB 1.1)
MultiMediaCard/Secure Digital interface
Smart Card interface (ISO7816)
Smart Battery Monitor Interface
Up to 64 General Purpose I/O Signals
Two 16-bit Pulse Width Modulators

□ Ten fully independent DMA Channels

Three Programmable Timers RTC Boot ROM Low Power Modes 5-Volt Tolerant Inputs



IMPORTANT NOTE: Please see http://www.sharpsma.com/ for errata on the LH7A404.



2.1.2 LH7A404 Microcontroller Block Diagram

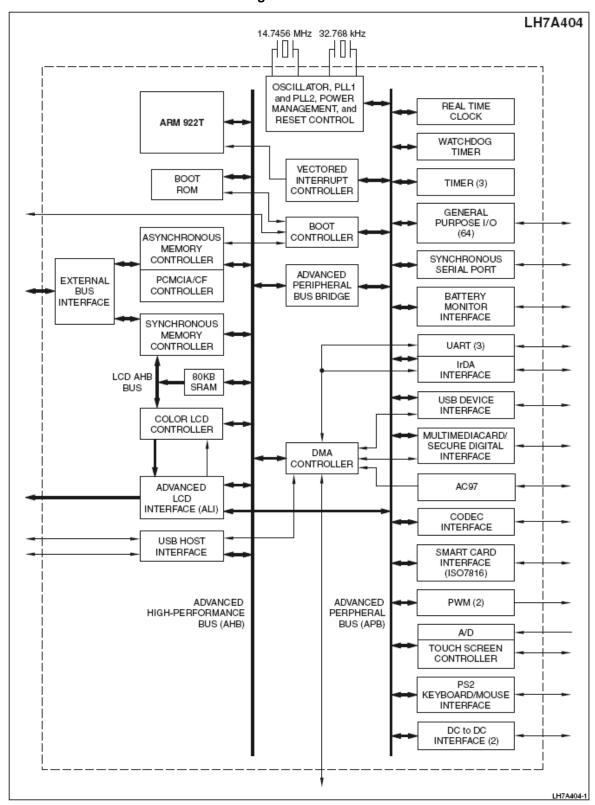


Figure 2.1: LH7A404 Microcontroller Block Diagram

2.2 Clocks

The LH7A404 requires 2 crystals in order to enable proper internal timing. The first, a 14.7456 MHz crystal, is used to generate many of the processor's internal clocks via a series of signal dividers. To generate the FCLK signal, for example, the 14.7456 MHz signal is run through a PLL in which the divisor is set in the Clock Set register. FCLK is then used internally as the Synchronous Bus Mode core clocking for the ARM922T core and cache. The 14.7456 MHz signal is also used to create the HCLK, HCLK_CPU, PCLK, and peripheral clock signals. One such peripheral clock is set up through a separate PLL to produce a 48.0 MHz clock for USB operations. An additional signal that stems from the crystal input is the uP_AUX_CLK signal; it is produced through a programmable divider on the Card Engine. The uP_AUX_CLK is provided on the 144-pin SODIMM expansion connector as the LH7A404 CLKOUT, and is set to a default of 14.7456MHz.

IMPORTANT NOTE: Please see Sharp's LH7A404 Universal Microcontroller User's Guide for additional information about the relationship between FCLK and HCLK.

The second required crystal runs at 32.768 kHz and is the only permanently running clock in the LH7A404. Because this clock runs regardless of the processor's state, a ripple divider is used in order to reduce power consumption during the halt and standby states. This divider produces the 1 Hz signal for the RTC interface as well as intermediate frequencies of 16 kHz and 8 kHz for the state controller and PLL interlocks.

The LH7A404 is able to operate in three different clocking modes: asynchronous, synchronous, or FastBus extension. Each of the three has certain advantages or disadvantages in system throughput and power consumption, depending on the whether the end application is CPU-, memory-, or peripheral-intensive. Refer to the LH7A400 Universal Microcontroller User's Guide for information on the specific advantages/disadvantages of each bus-clocking mode

The LH7A404's microcontroller core clock speed is initialized to 200 MHz on the Card Engine and the Bus speed is set at 100 MHz in the LogicLoader[™]. Other clock speeds can be supported and modified in software for specific user applications, such as a specific serial baud rate.

The LH7A404-11 Card Engine provides an external Bus clock, uP_BUS_CLK, on the 144-pin SODIMM connector. The uP_BUS_CLK, which is connected to the processor's SCLK, is set to a default of 100 MHz. SCLK also serves as the SDRAM and CPLD clock on the LH7A404-11 Card Engine.

LH7A404 Microcontroller Signal Name	LH7A404-11 Card Engine Net Name	Default Software Value in LogicLoader™
FCLK	N/A	200 MHz
HCLK	N/A	100 MHz
SCLK	uP_BUS_CLK	100 MHz
PGMCLK	uP_AUX_CLK	14.7456 MHz

2.3 Memory

2.3.1 Synchronous DRAM

The LH7A404-11 Card Engine uses a 32-bit memory bus to interface to SDRAM. The memory can be configured as 16, 32, or 64 MB in order to meet the user's memory requirements and cost constraints. Logic's default memory configuration on SDK boards is specified as 32 MB.

2.3.2 Direct Memory Access (DMA)

The Sharp LH7A404 microcontroller has an internal DMA controller that offers 10 fully independent channels. These channels can be used to interface streams from 20 internal peripherals to the system memory (including USB, SD/MMC, AAC, and all three UARTs). The DMA controller can also be used to interface streams from Memory to Memory or Memory to External Peripheral using 2 dedicated M2M channels. External handshake signals are available to support transfers to/from external peripherals. For more information on using the DMA refer to the LH7A404 Universal Microcontroller User's Guide.

2.3.3 NOR Flash

The LH7A404-11 Card Engine uses a 32-bit memory bus (split into 2, 16-bit channels, one to each flash memory) to interface to Intel StrataFlash memory chips. The onboard Card Engine memory can be configured as 8, 16, or 32 MB to meet the user's flash requirements and cost constraints. Logic's default flash configuration is 16 MB on the SDK. Because flash is one of the most expensive components on the LH7A404-11 Card Engine, it is important to contact Logic when determining the necessary flash size.

It is possible to expand the system's non-volatile storage capability by adding external flash IC's, CompactFlash, or NAND flash. See the LH7A404-11 Application Kit for reference designs or contact Logic for other possible peripheral designs.

2.3.4 NAND Flash

The LH7A404-11 Card Engine can be configured to boot from and use NAND flash. This functionality is currently under development, please contact Logic for more information.

2.3.5 EPROM

The LH7A404-11 Card Engine can be configured to boot from on board EPROM. This functionality is currently under development, please contact Logic for more information.

2.3.6 CompactFlash (memory-mapped mode only)

The LH7A404-11 Card Engine supports a CompactFlash memory-mapped mode only slot that compliments the processor's standard dual PC card support. The LH7A404-11 Card Engine uses the CPLD to provide the necessary signals for a CompactFlash card interface in memory-mapped mode only. The Zoom SDK reference design includes a CompactFlash connector for memory-mapped mode, but does not support hot-swappable capability. If hot-swappable capability is desired, it can be achieved by adding further hardware on the user's base-board. See the LH7A404-11 CPLD IO controller specification for further details on the use of CompactFlash.

IMPORTANT NOTE: The CPLD CompactFlash interface supports memory-mapped mode only. Use the LH7A404 processor's PC card slots for more PC card mode options.

2.4 Secure Digital (SD) and MultiMediaCard (MMC)

The LH7A404-11 Card Engine provides one SD/MMC adapter that can be used as an MMC card or SD card. This controller supports the full MMC/SD bus protocol identified in the MMC System Specification 2.11 and SD Memory Card Specification Version 1.0. The controller can also implement a SPI interface to either card. For more detailed operation and programming operations see the MultiMediaCard Association and SD Card System Specifications, available at www.mmca.org and www.sdcard.org. respectively.

2.5 PCMCIA/CompactFlash (external)

Both PCMCIA and CompactFlash devices are externally supported on the LH7A404 Card Engine. To handle these devices, the static memory controller has allocated two of the eight configurable memory banks for PCMCIA and CompactFlash interfaces. The Card Engine can directly support one PCMCIA/CompactFlash card and has the capability to interface to two cards with minimal external circuitry through the CPLD. In order to properly take advantage of these features software parameters need to be set; see Chapter 5: "Static Memory Controller" in the LH7A404 Universal Microcontroller User's Guide for more information.

2.6 10/100 Ethernet Controller

The LH7A404-11 Card Engine uses the SMSC 91C111 10/100 single chip Ethernet Controller to provide an easy-to-use networking interface. To facilitate use, six signals from the 91C111 are mapped to external connectors: transmit plus/minus, receive plus/minus, and two status LED's. The four analog PHY interface signals (transmit/receive) each require an external impedance matching circuit to operate properly. Logic provides an example circuit schematic in the LH7A404-11 Application Kit for reference.

IMPORTANT NOTE: The ENEEP signal on the SMSC 91C111 is connected to a zero ohm resistor that is not populated. This is because the ENEEP signal has a weak internal pull-up in the SMSC 91C111and if the signal is tied low it low will disable the serial EEPROM interface.

2.7 Audio CODEC

The LH7A404 processor has an internal AC97 controller that is compliant with the Audio CODEC '97 Component Specification, v2.2. This AC97 Controller implements a 5-pin serial interface to the AC97 Audio CODEC, in this case the Wolfson WM9708. From the Wolfson CODEC on the LH7A404-11 Card Engine there are 3 outputs, CODEC_OUTL, CODEC_OUTR, and MFP34 – MONO_OUT. All of these signals are available from the 80-pin expansion connectors.

NOTE: More information about the Intel AC97 standard is available on Intel's website at http://www.intel.com/design/chipsets/hdaudio.htm.

The Wolfson CODEC on the LH7A404 Card Engine performs full duplex 18-bit CODEC functions and supports variable sample rates from 8-48k samples/second. The Wolfson chip also has an onboard 24.576 MHz crystal which is used for the AC97 master clock frequency.

NOTE: The Sharp LH7A404 also offers an ACI interface for non-AC97 CODEC devices. This interface provides a digital 8-bit interface that is multiplexed with the signals from the AC97 controller. If you are looking for a different CODEC option, Logic has previously interfaced different high performance audio CODECs into other Card Engines. Contact Logic for assistance in selecting an appropriate audio CODEC for your application.

2.8 Video Interface

Sharp's LH7A404 microcontroller has a built in LCD controller supporting STN, Color STN, HR-TFT, AD-TFT, TFT panels at up to 800 x 600 x 16-bit or 1024 x 768 x 8-bit color resolution. See the LH7A404 Universal Microcontroller User's Guide for further information on the integrated LCD controller. The signals from the LH7A404's LCD controller are organized by bit and color and can be interfaced through the J1A expansion connectors. Logic has written drivers for numerous panels of different types and sizes. Please contact Logic before selecting a panel for your application.

IMPORTANT NOTE: Using the internal graphics controller will affect processor performance. Selecting display resolutions and color bits per pixel will vary processor busload.

2.9 Serial Interface

The LH7A404-11 Card Engine comes with the following serial channels: UARTA, UARTB, UARTC, and SSP. If additional serial channels are required, please contact Logic for reference designs. UARTC supports both wired serial and infrared communications, supporting a digital encoded output and decoded input without analog processing. Please see the LH7A404 Universal Microcontroller User's Guide for further information regarding serial communications.

2.9.1 UARTA

UARTA has been configured to be the LH7A404-11 development kit's main serial port. It is an asynchronous 16C550-compatible UART. This UART provides a high-speed serial interface that uses FIFO and is capable of sending and receiving serial data simultaneously. The signals from the Card Engine are TTL level signals not RS232 level. The user must provide an external RS232 transceiver for RS232 applications. Logic has provided an example reference design with the SDK kit. When choosing an RS232 transceiver, the user should keep in mind cost, availability, ESD protection, and data rates.

UARTA's baud rate is set by default to 115.2K bits/sec, though it supports all common serial baud rates from 2.4kbps to 460.8kbps. UARTA is available off the J1C 144-pin SODIMM connector.

2.9.2 UARTB

Serial Port UARTB is an asynchronous 16C550 compatible UART. This UART is a high-speed serial interface that uses FIFO, and it is capable of sending and receiving serial data simultaneously. The signals from the Card Engine are TTL level signals, not RS232 level. The user is responsible for providing an external RS232 transceiver for RS232 applications. UARTB's baud rate can be set to all common serial baud rates from 2.4kbps to 460.8kbps.

The UARTB pins are multiplexed with GPIO Ports B1-B5; when UARTB is not in use, the GPIO pins can be used instead. UARTB is available off the J1B 80-pin expansion connector.

2.9.3 **UARTC**

Serial Port UARTC has dual functionality; UARTC supports both serial communications (similar to UARTA/B) and infrared communications. When functioning as a serial port, UARTC will perform many of the characteristics as discussed for UARTA/B, except that UARTC does not have any status signals. If status signals are desired, it is necessary to map these control signals to GPIO ports.

In order to define UARTC's functionality, a programmable register is available to specify infrared or serial operation. Once one communication is chosen, the pins for the other connection are ignored, and vice-versa. The pins used for UARTC's functions are uP_IRTX and uP_IRRX (infrared) and uP_UARTC_RX and uP_UARTC_TX (serial), available off the J1B 80-pin expansion connector. Because there are two sets of transmission signals, UARTC's serial transmit and receive pins are multiplexed with GPIO Ports B0 and C0, becoming available GPIO pins when Infrared communications are not being used (the two sets of signals would otherwise be redundant). Refer to Sharp's LH7A404 Universal Microcontroller User's Guide for more information on using infrared communications.

2.9.4 SSP/SPI

The SSP interface on the LH7A404 Card Engine supports three data frame formats:

- □ Texas Instruments' SSI
- Motorola SPI
- National Semiconductor Microwire

Logic has chosen to implement Motorola's SPI interface as the default setting. If another interface is desired, programming the Control Register 0's 2-bit Frame Format field allows the default settings to be adjusted. The SPI format is used to interface between the parallel data inside the SoC and synchronous serial communications on slave peripheral devices. The SPI interface is master-only, with programmable clock rate and pre-scale options that are used to generate the appropriate bit-rate and Serial Clock output. The Data Size Specification is also configurable, and as such the SPI port can receive or transport anywhere from 4 to 16 bits. The SPI signals are available off the 144-pin SODIMM connector. Please see the LH7A404 Universal Microcontroller User's Guide for further information.

2.10 Keyboard and Mouse Interface (KMI)

The LH7A404 KMI implements a standard IBM PS2 or AT-compatible keyboard and mouse interface and complies with the AMBA specification rev 2.0. Communications with the KMI can be initiated through polling or interrupts. Furthermore, the interface offers a programmable clock divider, odd-bit parity generation/checking, and open drain outputs. Refer to Sharp's LH7A404 Universal Microcontroller User's Guide for more information about using a keyboard or mouse with the LH7A404-11 Card Engine.

2.11 USB Interface

The LH7A404 Card Engine is configured with both USB Host and Device functionality. The USB device interface is compliant to the USB 1.1 specification and both the OpenHCI and Intel UHCI specifications. This USB client supports full-speed (12 Mbits/sec) operation and both suspend and resume signaling. The USB device interface on the LH7A404 is able to transmit, receive data, or control information over the bus, and is available for external use off the J1A 80-pin connector.

The USB Host interface is compatible with both the USB 1.1 and OpenHCI 1.0 specifications. This controller also supports both low speed and high-speed USB devices and features a root hub with two downstream ports. The four signal USB connector signals are available off the J1A 80-pin connector while the host interface control functions are available can be accessed through jumper signals off the J1B 80-pin connector (see Section 5.4). For more information on using both the USB device and host interfaces, please see the LH7A404 Universal Microcontroller User's Guide for more information on using both the USB device and host interfaces.

IMPORTANT NOTE: In order for USB to be correctly implemented on the LH7A404 Card Engine, additional impedance matching circuitry is required on the USBP and USBM signals before they can be used. USB 1.1 requirements specify that the impedance on each driver must be between 28Ω and 44Ω . For reference, see the impedance matching circuit on the Logic SDK board.

2.12 ADC/Touch Interface

The LH7A404-11 Card Engine offers a 10-bit analog-to-digital converter (ADC). This ADC also can be used to implement a touch screen controller (TSC), supporting standard 4-wire resistive touch panels. This TSC supports up to 8-wire touch screens—if more than 4-wire operation is desired, please see the application note *Using the SHARP ADC with Resistive Touch Screens*, available at http://www.sharpsma.com/. The other six A/D signals are available externally off the J1A and J1B 80-pin connectors. Please see the LH7A404 Universal Microcontroller User's Guide for more information.

2.13 General Purpose I/O

Logic designed the LH7A404-11 Card Engine to be flexible and provided multiple options for analog and digital GPIO. There are numerous digital GPIO pins on the Card Engine that interface to the LH7A404 and the Xilinx CPLD. Some of these GPIO pins are interrupt capable while other signals are input or output only—see the Pin Descriptions section of this data sheet for more information on these options. If certain peripherals are not desired, such as the LCD Controller, Chip Selects, IRQs, UARTS, AC97, PCMCIA and CompactFlash, Smart Card Interface, or BMI interface, then multiple GPIO pins become available. Please see the table in Section 5.5 for a list of the available GPIO trade-offs.

2.14 CPLD

Please see the LH7A404-11 Card Engine IO Controller Specification for CPLD information.

2.15 Serial EEPROM Interface

Logic designed the LH7A404-11 Card Engine to have a low-cost 1 kbit serial EEPROM for non-volatile data storage. The serial EEPROM is connected to the LH7A404 microcontroller via the CPLD through an SPI interface – discussed in the touch screen controller section above. See Figure 2.2 below. For more information please view the LH7A404-11 Card Engine CPLD Interface Specification.



Figure 2.2: Serial EEPROM Block Diagram

2.16 Expansion/Feature Options

The LH7A404-11 Card Engine was designed for expansion and a variable feature set, providing all the necessary control signals and bus signals to expand the user's design. Some of these signals are buffered and brought out to the 144-pin SODIMM connector and two 80-pin expansion connectors. It is possible for a user to expand the Card Engine's functionality even further by adding PCI or ISA devices. Some features that are implemented on the LH7A404, but are not discussed herein, include: PWM, DC-DC, BMI, and ACI setup. See the LH7A404 Universal Microcontroller User's Guide and the LH7A404-11 Card Engine schematics for more detail. Logic has experience implementing additional options, including other audio codecs, Ethernet IC's, co-processors, and components on the Card Engine boards. Please contact Logic for potential reference designs before selecting your peripherals.

3 System Integration

3.1 Configuration

The LH7A404-11 Card Engine was designed to meet multiple applications for specific users and budget requirements. As a result, this Card Engine supports a variety of embedded operating systems and comes with the following hardware configurations:

- ☐ Flexible memory footprint: 16, 32, or 64 MB SDRAM
- ☐ Flexible flash footprint: 8, 16, or 32 MB StrataFlash
- Optional SMSC 91C111 10/100 Ethernet Controller
- □ Optional Wolfson WM9708 Audio CODEC

Please contact Logic for additional hardware configurations to meet your application needs.

3.2 Resets

3.2.1 Master Reset (Hard Reset)

All hardware peripherals should connect their hardware-reset pin to the MSTR_nRST signal on the SODIMM connector. Internally all Card Engine peripheral hardware reset pins are connected to either the MSTR_nRST net or to the RESET_HIGH net as shown in the figure below. The MSTR_nRST signal is an open-drain output, enabling the user to assert the MSTR_nRST signal externally. Logic suggests that custom designs implemented with the LH7A404-11 Card Engine use the MSTR_nRST signal as the "pin hole" reset used in commercial embedded systems.

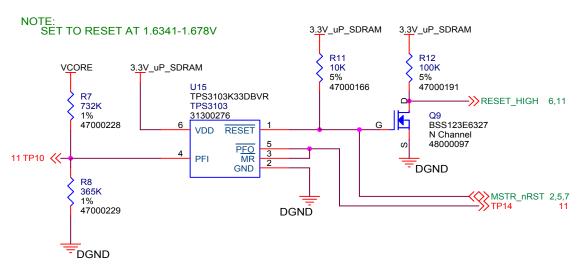


Figure 3.1: Reset Circuit

If the output of the reset chip, MSTR_nRST, is asserted (active low), the user can expect to lose information stored in SDRAM. The data loss occurs because the external signals uP_BUS_CLK and uP_AUX_CLK are interrupted during the assertion of the MSTR_nRST signal. The RESET_HIGH signal, on the other hand, is the active high output of the reset circuit and is not provided as part of the Card Engine connector interface.

IMPORTANT NOTE: Any custom reset circuit design should guard the assertion of the reset lines during a low power state so as to prevent power-up in a low or bad power condition (which will cause data corruption and possible temporary system lockup). See Section 3.5.2 for further details.

There following three conditions will cause a system-wide reset: power-on, a low pulse on the MSTR_nRST signal, and the power fail comparator input (PFI pin) falling below the internal comparator threshold.

Power On:

At power on, the MSTR_nRST signal is asserted low when the supply voltage (VDD) of the reset chip is between 0.4V and 2.941V. Once the 3.3V_uP_SDRAM supply surpasses 2.941V the reset chip will trigger a rising edge of MSTR_nRST after a 65 to 195ms delay (130 ms typical).

Low Pulse on MSTR_nRST Signal:

A low pulse on the MSTR_nRST signal of the reset chip, asserted by an external source (for example, the reset button on the custom design application) will bring MSTR_nRST low until the assertion source is de-asserted. There is no delay beyond the de-assertion of the external MSTR_nRST signal source, so the custom design must ensure that the assertion time is sufficient for all related peripherals.

Logic suggests that any external assertion source that triggers the MSTR_nRST signal, analog, or digital de-bouncing be used to generate a clean one shot reset signal.

Power Fail:

If the power fail comparator input pin (PFI pin) falls below the internal comparator threshold of 0.551V, it will create a low pulse on the MR input pin of the reset chip. The low assertion of the MR pin will assert the MSTR_nRST signal and will hold it low after the MR pin is de-asserted (PFI is above the comparator level and power is restored) for 65 to 195 ms (130 ms typical). Please see the TI TPS3103 data sheet at http://www.ti.com for additional details on reset timing and thresholds.

3.2.2 Soft Reset

Logic has created a soft reset signal, SW_nRESET, designated as a reset for the LH7A404's internal registers without affecting the peripherals on the rest of the board or the data stored in SDRAM. The data is saved because the SDRAM controller automatically places the SDRAM in self-refresh before the uP_SD_CLK clock is disabled. As in the Standby state described in Section 3.5.4.2, the 32.768 kHz clock continues running, allowing the system to properly wake up. The SW_nRESET signal is an input to the LH7A404 processor's user reset input pin.

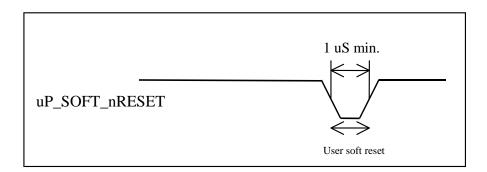


Figure 3.2: Soft Reset

See Sharp's LH7A404 Universal Microcontroller User's Guide for additional information on register conditions after a soft (manual) reset.

3.3 Interrupts

The LH7A404 incorporates two Vectored Interrupt Controllers (VIC1 and VIC2): the advantage being that a vectored interrupt has improved latency as it provides direct information where service routines are located, eliminating the need for levels of software arbitration. Through these two interrupt controllers the LH7A404 can prioritize and process up to 64 interrupts (40 internal). Figure 3.3 shows a list of the interrupt hierarchy, ordered by priority. All VIC1 interrupts have a higher priority than any VIC2 interrupts. In both VICs, FIQ interrupts have the highest priority, followed by interrupt vector 0 through interrupt vector 15; non-vectored IRQ interrupts have the lowest priority. Refer to Sharp's LH7A404 Universal Microcontroller User's Guide for further information on using IRQ and FIQ interrupts.

VIC	INTERRUPT TYPE
VIC1	FIQ Interrupt(s)
VIC1	Vectored Interrupts 0-15 (in that order)
VIC1	Non-vectored Interrupts
VIC2	FIQ Interrupt(s)
VIC2	Vectored Interrupts 0-15 (in that order)
VIC2	Non-vectored Interrupts

Figure 3.3: Interrupt Priorities (high to low)

NOTE: The CPLD interrupts the processor via the uP_nIRQE signal. This signal is a FIQ interrupt (PF4) in VIC2.

3.4 JTAG Debugger Interface

The JTAG connection on the LH7A404 allows recovery of corrupted flash memory and real time applications debug. When choosing a debugger board, remember that many different third-parties' JTAG debuggers are available for Sharp ARM microcontrollers. The following signals make up the JTAG interface to the LH7A404: uP_TDI, uP_TMS, uP_TCK, and uP_TDO. These signals should interface directly to a 20-pin 0.1" through-hole connector as demonstrated in the Sharp LH7A404 Universal Microcontroller User's Guide, or as shown on reference schematics.

IMPORTANT NOTE: When laying the 20-pin connector out, realize it may not be numbered as a standard 20-pin 0.1" IDC through-hole connector. See LH7A404-11 SDK reference design for further details. Different IC manufacturers define the 20-pin IDC connector pin-out differently.

IMPORTANT NOTE ON USING JTAG: The Sharp LH7A404 processor requires a rising edge on the processor wake-up signal to bring the processor from Cold Boot state to run state. Therefore, in order to use JTAG operation on the LH7A404-11 Card Engine, one must consult their JTAG manufacturer to find when the JTAG device requires the processor to be in the Run state. If the JTAG device issues a reset to the processor, then the wake-up signal must transition from low to high to return to the Run state before the JTAG debugger may connect. The JTAG device may be able to connect to the processor while it is in Standby state, but will not be able to do anything that requires processor functioning until woken.

3.5 Power Management

3.5.1 System Power Supplies

In order to ensure a flexible design, the LH7A404-11 Card Engine was designed to have the following five power areas, 3.3V_uP_SDRAM, 3.3V, 3.3VA, 3.3V_WRLAN, and VCORE. All power areas are inputs to the Card Engine with the exception of 3.3V_WRLAN, which is an output from the Card Engine.

3.5.1.1 3.3V_uP_SDRAM

The 3.3V_uP_SDRAM input pins are connected to a 3.3V power supply with an optional backup battery. If the design is required to maintain SDRAM contents in a critical power situation (low battery, loss of power), the 3.3V_uP_SDRAM supply should be maintained above the minimum level at all costs (see Section 2 "Electrical Specification"). Logic suggests using Standby mode to prepare the system for a critical power condition. In this way, the SDRAM is placed into self-refresh and processor is placed into the Standby state. Please note the description of Standby mode in this section below.

3.5.1.2 3.3V

The power nets connected to the 3.3V power plane handle the majority of the peripheral supply pins (digital) on the LH7A404-11 Card Engine. This supply must stay within the acceptable levels specified in the "Electrical Specification" section of this manual, unless experiencing power down or critical power conditions.

Under critical power conditions, Logic suggests notifying the system through the assertion of a Standby sequence first, and then powering this supply off.

3.5.1.3 3.3VA

The power nets connected to the 3.3VA power plane handles all peripheral supply pins (analog), but not the LH7A404 processor on the LH7A404-11 Card Engine. The 3.3VA supply must stay within the acceptable levels specified in the "Electrical Specification" section of this manual, unless powering down the board or under critical power conditions. Under critical power conditions, Logic suggests first notifying the system through the assertion of a Standby sequence and then powering this supply off.

3.5.1.4 3.3V_WRLAN

This "power" supply net is an output from the Card Engine and is controlled through a registered bit in the on-board CPLD. For more details on this specific control bit, see the *LH7A404 Card Engine IO Controller Specification* manual. Logic's software BSP asserts this signal in order to properly manage power in the LAN91C111 Ethernet chip. However, this management does not put the part in a low enough power state for many applications.

The custom application board should use the 3.3V_WRLAN output pin to supply the Ethernet impedance matching resistors with power. These resistors should not be connected to 3.3V directly or the entire Ethernet controller circuit on the Card Engine will try to power itself through the impedance matching resistors. Please see Logic's schematics for the SDK reference designs for details.

IMPORTANT NOTE: The purpose of the 3.3V_WRLAN power plane on the Card Engine is to power the 91C111 chip separately and allow for a complete, but independent, shut down. Furthermore, the 3.3V_WRLAN output from the Card Engine is required to completely isolate the LAN circuit so that it is not back powered through the impedance matching resistors.

3.5.1.5 VCORE

The analog power pins on the LH7A404 are connected to the VCORE voltage with low-pass filtering. The VCORE input pins are connected to a 1.8V power supply with an optional backup battery. If the design is required to maintain SDRAM contents in a critical power situation (low battery, loss of power), the VCORE supply should be maintained above the minimum level at all costs (see "Electrical Specification" section). Logic suggests using Standby mode to prepare the system for a critical power condition. In this way, the SDRAM is placed into self-refresh and the processor is placed into the Standby state. Please see the description of Standby mode later in this section.

3.5.2 System Power Management

Good power management design is important in any system development and embedded system design is no exception. In embedded system design, power management is typically one of the most complicated areas due to the dramatic effect it has on the product cost, performance, usability, and overall customer satisfaction. Many factors affect a power-efficient hardware design: power supply selection (efficiency), clocking design, IC and component selection, etc. The LH7A404-11 Card Engine was designed to keep these aspects in mind and provide maximum flexibility in software and system integration.

On the LH7A404 there are many different software configurations that drastically effect power consumption: microcontroller core clock frequency, microcontroller bus clock frequency, microcontroller peripheral clocks, microcontroller bus modes (asynchronous, synchronous, FastBus), microcontroller power management states (run, halt, standby), peripheral power states and modes, product user scenarios, interrupt handling, and display settings (resolution, backlight, refresh, bits per pixel, etc). These settings are typically initialized in the startup software routines and may be later modified in the operating system and application software. Information for these items can be found in the appropriate documents such as the *LogicLoader Muser's Manual* or appropriate BSP manual.

IMPORTANT NOTE: Most of the LH7A404-11 Card Engine hardware architecture was designed for low power battery operated applications. The Xilinx CPLD, on the LH7A404-11 Card Engine design, was chosen to optimize cost over power savings. If power-optimization is the primary goal of the design; please contact Logic for other design configurations in this area.

3.5.3 Peripherals

Most peripherals provide software programmable power states. Sometimes, however, these programmable power states may not be the best solution. The SMSC 91C111 controller, for example, has software programmable power states which may not be sufficient for some applications. In order to solve this problem, Logic has provided hardware to cut power to the 91C111 chip. Please see the appropriate data sheets and the *LH7A404-11 Card Engine IO Controller Specification* for more information.

The LH7A404-11 Card Engine was designed to have the following five power areas, 3.3V_uP_SDRAM, 3.3V, 3.3V_WRLAN, 3.3VA, and VCORE for a flexible hardware design. See Figure 3.3 below.

Logic Net Name	Required Input VDC	Notes
3.3V_uP_SDRAM	3.3VDC	Connects to the Processor's 3.3-volt pins and the SDRAM. This net can be used for battery powered or bridge battery applications that require the processor and the SDRAM to refresh.
3.3V	3.3VDC	Connects to the digital peripherals on the Card Engine.
3.3VA	3.3VDC	Connects to the Audio Codec on the Card Engine to provide a clean analog plane. The user may choose not to provide a clean analog plane depending on their performance requirements.
VCORE	1.8V	Connects to the processor core voltage. See information on each specific processor for the VCORE voltage. Many processors require different VCORE voltages for different operating frequencies, temperatures, etc.
3.3V_WRLAN	3.3V (This Pin is an output, see section 3.5.1.4)	Provides power to the SMSC 91C111 processor from the 3.3V area. The power to the 3.3V_WRLAN area is controlled by the signal WRLAN_ENABLE from the CPLD. See the IO Controller Specification for controlling this signal.

IMPORTANT NOTE: Because the power management on the SMSC 91C111 is not suitable for many applications, the PMOS FET was added to control power input into the wired LAN.

Figure 3.4: Power Plane Diagram

3.5.4 Microcontroller

The LH7A404 processor power management's scheme was designed to be easy to use. There are three power management states provided in the LH7A404 microcontroller: RUN, STANDBY, and HALT. Please see below for descriptions from all three states and the LH7A404 Universal Microcontroller User's Guide for more details

3.5.4.1 Run Mode

Run is the LH7A404-11 Card Engine's normal operating stat in which both oscillator inputs and all clocks are hardware enabled. The LH7A404 can enter Run mode from either the Standby or Halt states. From the Standby state, Run can be accessed on three conditions: a rising-edge on the wakeup pin (the uP_WAKEUP signal), an exit from the Clock Set register (after the clock divisor has been adjusted and the new clock output has stabilized), or the falling-edge of an interrupt (interrupts are active low). A Halt to Run transition occurs on the falling-edge of an interrupt (interrupts are active low). Power Fail, or on a user reset (see Figure 3.2: Soft Reset above).

IMPORTANT NOTE: Two seconds after a power on reset, a rising edge transition on the uP_WAKEUP signal is required to transition from Standby to Run mode. The uP_WAKEUP signal is pulled to 3.3V_uP_SDRAM on the Card Engine so a pushbutton tied to ground implementation can easily be used to provide the required low to high transition on the uP_WAKEUP signal. The SDK kit has example circuitry for the required uP_WAKEUP signal transition.

3.5.4.2 Standby Mode

Standby is the LH7A404 Card Engine's hardware power down mode, allowing for minimal power consumption. In this mode, only the 32.768 kHz clock input is enabled and the Real Time Clock and state controller are the only active functional blocks. Before all the clocks are turned off, however, the SDRAM is put into self-refresh mode, and maintains the contents of memory while in the low power state. Standby mode can only be entered after a system power-on or on a progression from the Run state. A Run to Standby transition occurs on a Power Fail, User Reset (Soft Reset), Write Clock Set (new clock divisors specified), or read of the STBY register.

3.5.4.3 Halt Mode

The Halt state is designed to reduce power consumption while the LH7A404 is waiting for an event such as a keyboard input. In this mode, although the processor clock is halted, the 14.7456 MHz oscillator input is enabled, thereby allowing software to specify the other active and inactive clocks. In this way, it is possible to maintain the LCD image yet reduce system-wide power usage at the same time. The only way to transition to the Halt state is on a read from the HALT register while in the Run state.

IMPORTANT NOTE: Although Halt consumes less power than Run mode, it consumes more power than the Standby Mode. Thus, on a power failure, the LH7A404 system will actually leave the Halt state and transition to the Standby state (the same thing occurs on an SW_nRESET.

3.6 ESD Considerations

The LH7A404-11 Card Engine was designed to interface to a customer's peripheral board. The Card Engine was designed to be low cost and adaptable to many different applications. The LH7A404-11 Card Engine does not provide any on-board ESD protection circuitry—this must be provided by the product it is used in. Logic has extensive experience in designing products with ESD requirements. Please contact Logic if you need any assistance in ESD design considerations.

4 Memory & I/O Mapping

4.1 SDRAM Memory Map

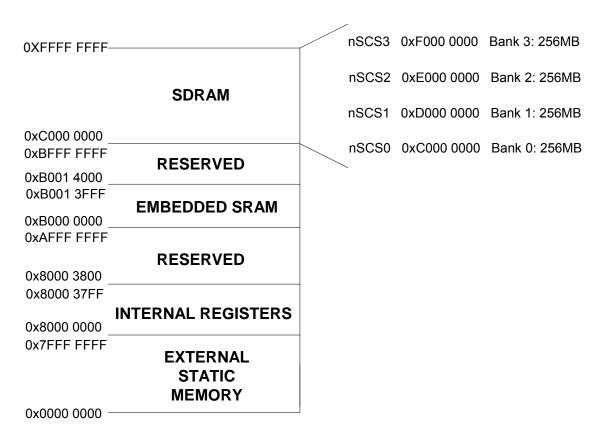


Figure 4.1: LH7A404 SDRAM Memory Map

4.2 External Static Memory Map

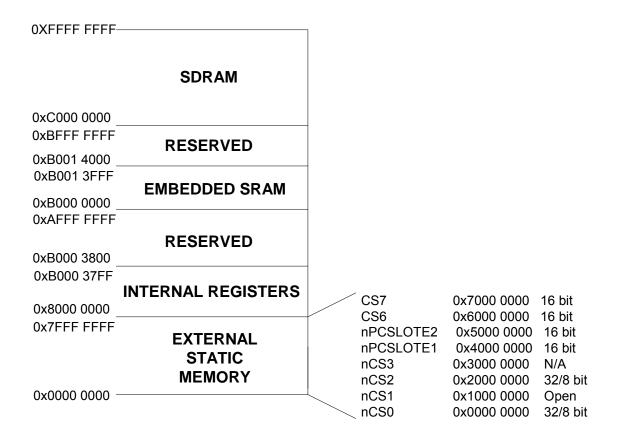


Figure 4.2: LH7A404 Static Memory Map

NOTE: The bit numbers refer to the bank width at reset. Banks 0 and 2 (nCS0 and nCS2) are 32-bits wide if flash is used as the boot device and 8-bits wide if an EEPROM is used as the boot device.

4.2.1 Card Engine Static Memory Map Description

The table below describes how each bank of external static memory is used on the Card Engine.

Bank	Chip Select	Start Address	Memory Description
7	CS7	0x7000 0000	IO Controller Peripherals (Fast¹)
6	CS6	0x6000 0000	IO Controller Peripherals (Slow¹)
5	nPCSLOTE2	0x5000 0000	Used for PC Card Interface
4	nPCSLOTE1	0x4000 0000	Used for PC Card Interface
3	nCS3	0x3000 0000	Open²
2	nCS2	0x2000 0000	Boot Device (Flash or Off-Board)
1	nCS1	0x1000 0000	Video
0	nCS0	0x0000 0000	Boot Device (Flash or Off-Board)

Notes:

- CPLD peripherals are components that get a decoded chip select from the CPLD. (i.e., CPLD memory mapped registers, onboard SMSC 91C111 Ethernet controller, etc. Please see the LH7A404-11 IO Controller Specification document for details.) These peripherals are separated into two different chip select banks, due to the difference in timing: slow and fast.
- 2. Chip Select 3 is multiplexed with the MultiMediaCard select signal.

4.2.2 Chip Select 6 (CS6)—CPLD Peripherals (slow timing)

The table below indicates how the CPLD decodes chip select 6. For more detailed information see the *LH7A404-11 IO Controller Specification*.

Address Range	Size	Memory Description
0x6000 0000 – 0x601F FFFF	2MB	Reserved
0x6020 0000 – 0x603F FFFF	2MB	CF Chip Select
0x6040 0000 – 0x605F FFFF	2MB	ISA-like Bus Chip Select
0x6060 0000 – 0x61FF FFFF	2MB (x13)	Reserved - On-Board Expansion
0x6200 0000 – 0x62FF FFFF	1MB (x16)	Reserved - Off-Board Expansion
0x6300 0000 – 0x63FF FFFF	1MB (x16)	Open - Available for User

4.2.3 Chip Select 5 (CS7)—CPLD Peripherals (fast timing)

The table below indicates how the CPLD decodes chip select 7. For more detailed information see the *LH7A404-11 IO Controller Specification*.

Address Range	Size	Memory Block Description
0x7000 0000 – 0x701F FFFF	2MB	Wired LAN Chip Select
0x7020 0000 – 0x703F FFFF	2MB	Card Engine Control Reg
0x7040 0000 – 0x705F FFFF	2MB	Reserved
0x7060 0000 – 0x707F FFFF	2MB	Reserved
0x7080 0000 – 0x709F FFFF	2MB	Reserved
0x70A0 0000 – 0x70BF FFFF	2MB	EEPROM SPI Reg
0x70C0 0000 – 0x70DF FFFF	2MB	Interrupt/Mask Reg
0x70E0 0000 – 0x70FF FFFF	2MB	Mode Reg
0x7100 0000 – 0x711F FFFF	2MB	FLASH Reg
0x7120 0000 – 0x713F FFFF	2MB	Power Management Reg
0x7140 0000 – 0x715F FFFF	2MB	IO Controller Code Revision Reg
0x7160 0000 – 0x717F FFFF	2MB	Extended GPIO Reg
0x7180 0000 – 0x719F FFFF	2MB	GPIO Data Reg
0x71A0 0000 – 0x71BF FFFF	2MB	GPIO Direction Reg
0x71C0 0000 – 0x71FF FFFF	2MB (X2)	Reserved - On-Board Expansion
0x7200 0000 – 0x72FF FFFF	1MB (X16)	Reserved - Off-Board Expansion
0x7300 0000 – 0x73FF FFFF	1MB (X16)	Open – Available for User

5 Pin Descriptions & Functions

IMPORTANT NOTE: The following pin descriptions and states are described after the initialization of the LogicLoader[™] (bootloader). Many of the signals defined in the tables below can be configured as input or outputs—all GPIOs on the LH7A404 can be configured as either inputs or outputs—or active low/high, and have different functions. It is critical to review all signals in the final design (both electrical and software) to verify the necessary configuration (external pull ups/pull downs).

In addition, keep in mind that the following mode line numbers on the Card Engine do not necessarily line up with the mode line numbers on the processor.

5.1 J1C Connector SODIMM 144-Pin Descriptions

J1C			
Pin#	Signal Name	1/0	Description
			This input pair receives 10/100 MB/s Manchester encoded data from the
1	ETHER_RX(-)	ı	10/100 BASE-T receive lines. Route as differential pair with ETHER_RX(+).
			Active Low. Driven low during power on in order to initiate a hard reset,
			erasing the contents of external memory. Refer to the reset description
			found in section 3.2.1 for more information on how this signal is driven.
			Drives the processor's nPOR line and every peripheral on the Card Engine with a reset line is reset with the assertion of this signal. Refer to the
			processor datasheet for register power-on reset states. This signal is pulled
2	MSTR nRST	ı	up to 3.3V_uP_SDRAM through a 10K resistor.
	MOTIC_IIICOT	•	This input pair receives 10/100 MB/s Manchester encoded data from the
3	ETHER RX(+)	ı	10/100 BASE-T receive lines. Route as differential pair with ETHER RX(-).
		-	Active Low. This signal initiates a soft reset (manual reset) – external
			memory contents are retained during reset. Drives processor's nURESET
			line. Supporting software must be implemented in order to function properly.
4	uP_SW_nRESET	- 1	This signal is pulled up to 3.3V_uP_SDRAM through a 33K resistor.
			This output pair drives 10/100 Mb/s Manchester-encoded data to the 10/100
5	ETHER_TX(-)	0	BASE-T transmit lines. Route as differential pair with ETHER_TX(+).
			Active Low. Buffered chip-select for asynchronous memory area 7 - the "fast
			peripheral" chip-select area. This signal is an output from the CPLD.
			Therefore when the CPLD does not decode an address that relates to the
			CPLD registers in the "fast peripheral" register set, it asserts FAST_nMCS.
	FACT -MOO		See the LH7A404-11 IO Controller Specification for addresses that are
6	FAST_nMCS	0	decoded by the CPLD.
7	ETHER TX(+)	0	This output pair drives 10/100 Mb/s Manchester-encoded data to the 10/100 BASE-T transmit lines. Route as differential pair with ETHER_TX(-).
	EIRER_IX(+)	U	Active Low. Buffered chip-select for asynchronous memory area 6 - the
			"slow peripheral" chip-select area. This signal is an output from the CPLD.
			Therefore when the CPLD does not decode an address that relates to the
			CPLD registers in the "slow peripheral" register set, it asserts SLOW nMCS.
			See the LH7A404-11 IO Controller Specification for addresses that are
8	SLOW_nMCS	0	decoded by the CPLD.
9	DGND	ı	Digital Ground (0V)
	-		Active Low. Buffered chip-select for asynchronous memory area 1. This is
10	VIDEO_nMCS	0	the "video" chip select area.
			Active Low open drain output. 24mA sink. This output indicates transmission
			or reception of frames or detection of a collision. This signal may be
11	ACT_LED/LAN_LED1	0	connected directly to an external LED.
			Active Low. This signal is the chip select for an off-board memory device.
			When uP_MODE3 line is low this device is located in asynchronous memory
			area 0. When uP_MODE3 is high this device is located in asynchronous
12	BOOT PMCS		memory area 2. See the <i>LH7A404-11 IO Controller Specification</i> for further
12	BOOT_nMCS	U	details.

J1C			
Pin#	Signal Name	I/O	Description
13	LNK LED/LAN LED2	0	Active Low open drain output. 24mA sink. This output indicates valid link pulses. This signal may be connected directly to an external LED.
			Active Low. The CPLD ISA-like Bus Logic decodes this Write signal. This
			signal is used to notify CompactFlash and ISA peripherals in area 6 of valid
11	nIOWD		data during a bus cycle. See the <i>LH7A404-11 IO Controller Specification</i> for
14	nIOWR	0	further details. Active Low. CPLD Power Management Register signal. Software must be
			implemented on the processor in order for this signal to operate properly. A
			low nSTANDBY signal will generate an interrupt in the processor. Software
			will cause the LH7A404-11 to enter standby mode (hardware power down),
			where the contents of the SDRAM are placed in self-refresh and will be maintained. See the <i>LH7A404-11 IO Controller Specification</i> for further
15	uP nSTANDBY		details. This signal is pulled up to 3.3V_uP_SDRAM through a 33K resistor.
	_		Active Low. The CPLD ISA-like Bus Logic decodes this Read signal. This
			signal is used to request CompactFlash and ISA peripherals in area 6 to
40	-IODD		drive data during a bus cycle. See the <i>LH7A404-11 IO Controller</i>
16 17	nIORD DGND	0	Specification for further details. Digital Ground (0V)
- ' '	DOND		Power Supply (3.3V) from the 10/100 wired LAN circuit. This pin is used to
			power the impedance matching resistor network on the Ethernet's TX and
			RX lines. It should not be connected to anything else. It may be shut down
10	3.3V WRLAN		when appropriate (software controlled to cut power off to the wired LAN circuit). See Section 3.5.1.
18 19	3.3V_VKLAN		Power Supply (3.3V). See section 3.5.1.
-13	0.01		Active High. Buffered Address Latch Enable. This signal is driven high to
			indicate when the MA<19:0> signal lines are valid or the processor data bus
20	BALE	0	is in use. See the <i>LH7A404-11 IO Controller Specification</i> for further details.
			Active Low. This is connected to the processor WAKEUP pin. The LH7A404-11 implements an Auto Wakeup circuit to enable this line. This signal is
21	uP WAKEUP		pulled up to 3.3V_uP_SDRAM through a 33K resistor.
	_		Active Low. This line can be asserted by an ISA-like or CompactFlash
			device. When asserted low, this generates a low on the uP_WAIT signal to
			the processor. See the <i>LH7A404-11 IO Controller Specification</i> for further
22	nCHRDY		details and timing diagrams. This signal is pulled up to 3.3V through a 1K resistor.
			Active Low. Dedicated hardware interrupt (INT4) on the processor. May also
			be configured as a GPIO pin. See Section 5.5. This signal is pulled up to
23	uP_nIRQD	I	3.3V_uP_SDRAM through a 33K resistor.
			This is connected to Test Mode Pin 0 on the processor. This signal needs to be pulled high for normal operation and low for JTAG use. Please see the
			section on Operating Modes in the processor's datasheet for detailed
			operation. This signal is pulled up to 3.3V_uP_SDRAM through a 33K
24	uP_TEST1		resistor.
			Active Low. Dedicated hardware interrupt (INT2) on the processor. May also be configured as a GPIO pin. See Section 5.5. This signal is pulled up to
25	uP nIRQC	ı	3.3V_uP_SDRAM through a 33K resistor.
			This is connected to Test Mode Pin 1 on the processor. This signal needs to
			be pulled high for both normal operation and for JTAG use. Please see the
			section on Operating Modes in the processor's datasheet for detailed operation. This signal is pulled up to 3.3V_uP_SDRAM through a 33K
26	uP TEST2	ı	resistor.
			Active Low. Dedicated hardware interrupt (INT1) on the processor. May also
			be configured as a GPIO pin. See Section 5.5. This signal is pulled up to
27	uP_nIRQB	I	3.3V_uP_SDRAM through a 33K resistor.

J1C						
	Signal Name	I/O	Description			
			Active Low. Driven low during power on in order to initiate a hard reset, erasing the contents of external memory. Refer to the reset description found in Section 3.2.1 for more information on how this signal is driven. Drives the processor's nPOR line and every peripheral on the Card Engine with a reset line is reset with the assertion of this signal. Refer to the processor datasheet for register power-on reset states. This signal is pulled			
28	MSTR_nRST	I	up to 3.3V_uP_SDRAM through a 10K resistor.			
29	uP nIRQA		Active Low. Dedicated hardware interrupt (INT0) on the processor. May also be configured as a GPIO pin. See Section 5.5. This signal is pulled up to			
23	ui _nii\QA	'	3.3V_uP_SDRAM through a 33K resistor. JTAG Test Mode Select Input. May leave unconnected if not using the JTAG			
30	uP_TMS	I	port. This signal is pulled up to 3.3V_uP_SDRAM through a 10K resistor. No internal connection (not implemented on the LH7A404-11)			0K resistor.
31		NC	JTAG Test Data Ser			C port is not in
32	uP TDO	0	use. This signal is pu			
33	<u> </u>		No internal connection			ore registor.
- 55		110	JTAG Test Serial Da			ing the JTAG
34	uP_TDI	ı	port. This signal is p			
35		NC	No internal connection	on (not implemented	on the LH7A404-11)	
00	D. TOK		JTAG Test Clock Inp			
36	uP_TCK		This signal is pulled Active low. This is th			
			ISA I/O Ready signa			
			Controller Specificat			
37	uP_nWAIT	ı	3.3V_uP_SDRAM th			-
			Boot device signal. I			
00	D MODEO	١.	external device. This	s signal is pulled up to	o	through a 33K
38	uP_MODE3	ı	resistor. This is a CRIO signal (RC4) that is used to implement the "Ready To Sand"			
			This is a GPIO signal (PC4) that is used to implement the "Ready To Send" line for the processor's UART2 interface. See Section 2.9. May also be			
39	uP UARTA RTS	0	configured as a GPIO pin. See Section 5.5.			
			This pin can also be used as a General Purpose input and read from the			
			CPLD Mode register. See the LH7A404-11 IO Controller Specification for			
4.0	D 140DE0	١.	further details. This s	signal is pulled up to	3.3V_uP_SDRAM th	rough a 33K
40	uP_MODE2	I	resistor.	Cond" line for the nu	annon's LIADTO int	arface Coo
41	uP UARTA CTS	1	This is the "Clear To Send" line for the processor's UART2 interface. See Section 2.9. This signal is pulled down to DGND through a 33K resistor.			
	<u> </u>	† ·	Coolon 2.0. This dig	nario panea aeviri te	BOND anough a oo	TC TCCICTOT.
			Mode1	Mode0	Bus Width	
			0	0	8-bit	
			0	1	16-bit	
			1	0	32-bit (default)	
			0 # ///7/404 4	1 10 0	32-bit	
			See the <i>LH7A404-1</i> sheet for further deta			
42	uP MODE1	ı	through a 10K resist		iled up to 3.3v_ui _3	DIVAIVI
	<u> </u>		This is the "Transmit		or's UART2 interface	. See Section
43	uP_UARTA_TX	0	2.9. This signal is pu	lled up to 3.3V throu	gh a 33K resistor.	
			Mode1	Mode0	Bus Width	
			0	0	8-bit	
			0	1	16-bit	
			1	0	32-bit (default)	
			See the <i>LH7A404-1</i>	1 IO Controller Speci	32-bit	ecor'e data
			sheet for further deta			
44	uP_MODE0	1	resistor.	Triio digital la pul	GOMII IO DOND (I	Jugii u Toix
45	uP UARTA RX	ı	This is the "Receive" line for the processor's UART2 interface. See Section 2.9. This signal is pulled up to 3.3V through a 33K resistor.			
	ui _0/1/1//_1//	<u> </u>	ıε.σ. Tiliə siyilal is pu	iica up io 3.37 iiii0u	gir a oort resisior.	

J1C					
	Signal Name	1/0	Description		
#	Olgital Name	","	The DMA Request 1 line. This signal is pulled to DGND through a 33K		
46	uP DREQ1	0	resistor.		
47			No internal connection (not implemented on the LH7A404-11)		
			The DMA Request 0 line. This signal is pulled to DGND through a 33K		
48	uP_DREQ0	0	resistor.		
			This is the "Data Set Ready" line for the processor's UART2 interface. See		
49	uP_UARTA_DSR		Section 2.9. This signal is pulled up to 3.3V through a 33K resistor.		
50		NC	No internal connection (not implemented on the LH7A404-11)		
			Active Low. CPLD Power Management Register signal. Software must be		
			implemented on the processor in order for this signal to operate properly. A low nSUSPEND signal will generate an interrupt in the processor. Software		
			will cause the LH7A404-11 to enter suspend mode (hardware power down),		
			where the contents of the SDRAM are placed in self-refresh and will be		
			maintained. See the LH7A404-11 IO Controller Specification for further		
51	nSUSPEND	1	details. This signal is pulled up to 3.3V_uP_SDRAM through a 33K resistor.		
52		NC	No internal connection (not implemented on the LH7A404-11)		
			This signal is a programmable auxiliary clock that is set to 14.7456 (max		
53	uP_AUX_CLK	0	value) by default. See Section 2.2.		
E 4	UP DACKI		The DMA Acknowledge 1 line. This signal is pulled to DGND through a 33K		
54 55	uP_DACK1 DGND	0	resistor. Digital Ground (0V)		
55	DGND	<u> </u>	The DMA Acknowledge 0 line. This signal is pulled to DGND through a 33K		
56	uP DACKO	0	resistor.		
- 00	ar _briefic	+~	CPU core voltage supply (on during low power, uP_SW_Reset). VCORE is		
57	VCORE	1	fixed at 1.8V.		
			CPU core voltage supply (on during low power, uP_SW_Reset). VCORE is		
58	VCORE	I	fixed at 1.8V.		
			CPU core voltage supply (on during low power, uP_SW_Reset). VCORE is		
59	VCORE	I	fixed at 1.8V.		
00	VOORE	١.	CPU core voltage supply (on during low power, uP_SW_Reset). VCORE is		
60	VCORE	1	fixed at 1.8V. uP and SDRAM Power Supply (3.3 V) (on during low power,		
			uP_SW_Reset). Recommend leaving this supply as the only powered		
61	3.3V_uP_SDRAM	ı	supply during Standby power down mode.		
			uP and SDRAM Power Supply (3.3 V) (on during low power,		
			uP_SW_Reset). Recommend leaving this supply as the only powered		
62	3.3V_uP_SDRAM	I	supply during Standby power down mode.		
			uP and SDRAM Power Supply (3.3 V) (on during low power,		
00	0.01/	١.	uP_SW_Reset). Recommend leaving this supply as the only powered		
63	3.3V_uP_SDRAM	I	supply during Standby power down mode.		
			uP and SDRAM Power Supply (3.3 V) (on during low power, uP SW Reset). Recommend leaving this supply as the only powered		
64	3.3V uP SDRAM	1	supply during Standby power down mode.		
		<u> </u>	SPI Fame signal. This signal is connected directly to the processor's		
			SSPFRM signal. It is used to mark the beginning and end of a frame. See		
65	uP_SPI_FRM	0	the processor's data sheet for further details.		
			Synchronous Memory Clock. This clock operates at 100MHz and is		
66	uP_BUS_CLK	0	connected to the SDRAM as well as the CPLD. See Section 2.2.		
			SPI Transmit signal. This signal is connected directly to the processor's		
67	uD CDI TV		SSPTX signal. It is used to transmit serial data. See the processor's data		
67 68	uP_SPI_TX DGND		sheet for further details. Digital Ground (0V)		
- 50	DOMD	+'-	SPI Receive signal. This signal is connected to the processor's SSPTX		
			signal. It is used to receive serial data. See the processor's data sheet for		
69	uP_SPI_RX	1	further details. This signal is pulled up to 3.3V through a 33K resistor.		
			Synchronous Memory Row Address Strobe Signal. This signal is used in		
			synchronizing all SDRAM into row addressing mode. This signal has a 22-		
70	uP_nRAS	0	OHM series resistor.		

14.0						
J1C Din #	Signal Name	1/0	Description			
71	uP_SPI_SCK	0	SPI clock signal. This signal is connected directly to the processor's MMSPICLK signal. SPI transmit/receive data is valid on the rising edge of this clock (data is output from one falling edge to the next and clocked in on the rising edge). See the processor's data sheet for further details.			
70	D ~CAC		Synchronous Memory Column Address Strobe Signal. This signal is used in synchronizing all SDRAM into column addressing mode. This signal has a			
72 73	uP_nCAS uP MD0		22-OHM series resistor.			
73	UP_IVIDU		Buffered Data Bus bit 0.			
74	uP nMWE3		Active low. Buffered write enable for buffered data bus bits 16->31 to the Flash.			
75	uP MD1		Buffered Data Bus bit 1.			
76	uP_nMWE2		Active low. Buffered Byte Lane Enable 2 signal. This signal is supplied for off-board use in order to implement memory devices of varying widths.			
77	uP_MD2		Buffered Data Bus bit 2.			
			Active low. Buffered Byte Lane Enable 1 signal. This signal is supplied for			
78	uP_nMWE1		off-board use in order to implement memory devices of varying widths.			
79	uP_MD3		Buffered Data Bus bit 3.			
80	uP nMWE0		Active low. Buffered write enable for buffered data bus bits 0->15 to the flash.			
81	uP MD4		Buffered Data Bus bit 4.			
01			Active low. This buffered signal from the CPLD is the processor's write enable line. See the LH7A404-11 IO Controller Specification for further			
82	uP_nMWR		details.			
83	uP_MD5		Buffered Data Bus bit 5.			
84	uP_nMRD	0	Active low. This buffered signal is the Flash Read signal.			
85	uP_MD6		Buffered Data Bus bit 6.			
86 87	uP_MA27 uP MD7		Buffered Address Bus bit 27.			
88	uP_MD7 uP_MA26		Buffered Data Bus bit 7. Buffered Address Bus bit 26.			
89	DGND		Digital Ground (0V)			
90	uP MA0		Buffered Address Bus bit 0.			
91	uP MD8		Buffered Data Bus bit 8.			
92	uP MA1		Buffered Address Bus bit 1.			
93	uP_MD9	I/O	Buffered Data Bus bit 9.			
94	uP_MA2	0	Buffered Address Bus bit 2.			
95	uP_MD10		Buffered Data Bus bit 10.			
96	uP_MA3		Buffered Address Bus bit 3.			
97	uP_MD11		Buffered Data Bus bit 11.			
98	uP_MA4		Buffered Address Bus bit 4.			
99 100	uP_MD12 uP MA5		Buffered Data Bus bit 12. Buffered Address Bus bit 5.			
101	uP MD13		Buffered Data Bus bit 13.			
102	uP MA6		Buffered Address Bus bit 6.			
103	uP MD14		Buffered Data Bus bit 14.			
104	uP MA7		Buffered Address Bus bit 7.			
105	uP_MD15	I/O	Buffered Data Bus bit 15.			
106	uP_MA8	0	Buffered Address Bus bit 8.			
107	3.3V		Power Supply (3.3V)			
108	uP_MA9		Buffered Address Bus bit 9.			
109	DGND		Digital Ground (0V)			
110	uP_MA10		Buffered Address Bus bit 10.			
111	uP_MD16 uP MA11		Buffered Data Bus bit 16. Buffered Address Bus bit 11			
112 113	uP_MATT uP_MD17		Buffered Address Bus bit 11. Buffered Data Bus bit 17.			
114	uP MA12		Buffered Address Bus bit 12.			
115	uP MD18		D Buffered Data Bus bit 18.			
116	uP_MA13		Buffered Address Bus bit 13.			

J1C							
Pin#	Signal Name	1/0	Description				
117	uP_MD19	I/O	Buffered Data Bus bit 19.				
118	uP_MA14	0	Buffered Address Bus bit 14.				
119	uP_MD20	I/O	Buffered Data Bus bit 20.				
120	uP_MA15	0	Buffered Address Bus bit 15.				
121	uP_MD21	I/O	Buffered Data Bus bit 21.				
122	uP_MA16	0	Buffered Address Bus bit 16.				
123	uP_MD22	I/O	Buffered Data Bus bit 22.				
124	uP_MA17	0	Buffered Address Bus bit 17.				
125	uP_MD23	I/O	Buffered Data Bus bit 23.				
126	uP_MA18		Buffered Address Bus bit 18.				
127	DGND	I	Digital Ground (0V)				
128	uP_MA19	I/O	Buffered Address Bus bit 19.				
129	uP_MD24		Buffered Data Bus bit 24.				
130	uP_MA20		Buffered Address Bus bit 20.				
131	uP_MD25		Buffered Data Bus bit 25.				
132	uP_MA21	0	Buffered Address Bus bit 21.				
133	uP_MD26	I/O	Buffered Data Bus bit 26.				
134	uP_MA22		Buffered Address Bus bit 22.				
135	uP_MD27	I/O	Buffered Data Bus bit 27.				
136	uP_MA23		Buffered Address Bus bit 23.				
137	uP_MD28		Buffered Data Bus bit 28.				
138	uP_MA24	_	Buffered Address Bus bit 24.				
139	uP_MD29		Buffered Data Bus bit 29.				
140	uP_MA25	0	Buffered Address Bus bit 25.				
141	uP_MD30	I/O	Buffered Data Bus bit 30.				
			Active Low. The CPLD Chip Select Logic decodes this Address Enable				
142	nAEN		signal. See the <i>LH7A404-11 IO Controller Specification</i> for further details.				
143	uP_MD31	I/O	Buffered Data Bus bit 31.				
144	3.3V		Power Supply (3.3V)				

5.2 J1A Expansion Connector Pin Descriptions

J1A					
	Signal Name	1/0	Description		
1	LCD VSYNC - LCD SPS		LCD VSYNC (TFT Signal).		
2	LCD_HSYNC - LCD_HRLP		LCD HSYNC (TFT Signal).		
3	LCD_DCLK	0	LCD Panel Data Clock. This signal has a 22-OHM series resistor.		
			This is a GPIO signal (PC5) that is used to implement the "Display ON" line		
			for the LCD interface. May also be configured as a GPIO pin. See Section		
	LCD_DON		5.5.		
5	LCD_MDISP	0	LCD enable signal (TFT signal).		
	LOD VEEEN		Active high. This is a GPIO signal (PC3) that is used to implement a "VEE Enable" signal or Backlight Control signal for the LCD interface. May also be		
7	LCD_VEEEN LCD_VDDEN		configured as a GPIO pin. See Section 5.5. Active high. This signal is the LCD panel Vcc enable.		
	LCD_VDDEN	U	This is the external clock input line for LCD controller. This signal is pulled to		
8	LCD_CLK_RETURN	١,	DGND through a 33K resistor.		
9	DGND		Digital Ground (0V)		
	50.15		LCDCLS Signal Output (Row Driver Clock) This signal is only used with a		
10	LCD CLS	0	HR-TFT interface.		
11	LCD_VSYNC - LCD_SPS		LCD SPS function.		
			LCDPS Signal Output (Power Save)-This signal is only used with a HR-TFT		
12	LCD_PSAVE	0	interface.		
	-		LCDSPL Signal Output (Start Pulse Left) – This signal is only used with the		
			HR-TFT interface.		
			NOTE: This signal is only used when the jumper (JP23) is connected to the		
13 (+)	LCD_SPL	0	positive terminal.		
			LCDSPR Signal Output (Start Pulse Right) – This signal is only used with		
			the HR-TFT interface.		
12 ()	LCD SPR		NOTE: This signal is only used when the jumper (JP23) is connected to the negative terminal.		
	LCD_SFK LCD HSYNC - LCD HRLP		LCD HSYNC (TFT Signal).		
	LCD MOD		LCD MOD signal used by the row driver (TFT signal).		
13	<u>EGD_MOD</u>		LCDREV Signal Output (Grey Scale Voltage Reverse) – This signal is only		
16	LCD REV	0	used with the HR-TFT interface.		
			This is a GPIO (PE6) signal that is used for status/debug LEDs on the		
17	uP_STATUS_1	0			
			This is a GPIO (PE7) signal that is used for status/debug LEDs on the		
18	uP_STATUS_2		Application Board. May also be configured as a GPIO pin. See Section 5.5.		
			AC97 Serial Interface Clock input from an AC97 compliant audio codec.		
19	uP_AC97_BITCLK	ı	This signal is pulled down to DGND through a 33K resistor.		
		_	Active Low. AC97 Reset line output to an AC97 compliant audio codec. This		
20	uP_AC97_nRESET		signal is pulled up to 3.3V through a 33K resistor.		
			AC97 Serial Interface Sync pulse output to an AC97 compliant audio codec.		
			The codec Frequency is set on codec to be 48 KHz, while the default frequency for the sync is set up to be 2.9491 MHz (14.7456 MHz / 5) on the		
21	uP AC97 SYNC		processor.		
	<u> </u>		AC97 Serial Data input from an AC97 compliant audio codec. This signal is		
22	uP_AC97_SD_IN	ı	pulled down to DGND through a 33K resistor.		
23	uP_AC97_SD_OUT	0	AC97 Serial Data output to an AC97 compliant audio codec.		
24	DGND	Ī	Digital Ground (0V)		
25	uP A/D1	ı	This signal is the input to channel 4 of the Processor's 10-bit A/D converter.		
26	uP A/D2	ı	This signal is the input to channel 5 of the Processor's 10-bit A/D converter.		
27	AGND	Ī	Analog Ground (0V)		
28	MFP39 - uP A/D3	ı	This signal is the input to channel 6 of the Processor's 10-bit A/D converter.		
29	MFP40 - uP A/D4		This signal is the input to channel 7 of the Processor's 10-bit A/D converter.		
30	3.3VA		Analog Power Supply (3.3V)		
_	CODEC INL		Left channel stereo line input of the audio codec.		
31 32	CODEC_INL		Right channel stereo line input of the audio codec.		
32	CODEC_INK		ומקות החמוווסו אוסיסט ווווס ווויףעניטו נווס מעעוט נטעפט.		

14.4						
J1A Pin #	Signal Name	1/0	Description			
Γ III #	Signal Name		Left stereo mixer-channel line output. Please see the Wolfson #WM9708			
33	CODEC_OUTL		AC97 Revision 2.1 Audio Codec Technical Datasheet for more details.			
			Right stereo mixer-channel line output. Please see the Wolfson #WM9708			
34	CODEC_OUTR		AC97 Revision 2.1 Audio Codec Technical Datasheet for more details.			
35	AGND		Analog Ground (0V)			
36	TOUCH_LEFT		This is the Y+ position input to the four-wire resistive touch screen controller.			
37	TOUCH_RIGHT		This is the Y- position input to the four-wire resistive touch screen controller.			
38 39	TOUCH_BOTTOM TOUCH TOP		This is the X+ position input to the four-wire resistive touch screen controller. This is the X- position input to the four-wire resistive touch screen controller.			
40	3.3VA		Analog Power Supply (3.3V)			
40	3.3VA	- '	The LCD data bus used to transmit data to the LCD module. Note that R0 is			
			an intensity bit for the LCD display and therefore is tied to the other intensity			
			bits, B0 and G0, which are connected to LCD_D15 on the processor. May			
41	R0		also be configured as a GPIO pin. See Section 5.5.			
			The LCD data bus used to transmit data to the LCD module. RED 1 is			
42	R1	0	connected to LCD_D0.			
43	R2		The LCD data bus used to transmit data to the LCD module. RED 2 is connected to LCD D1.			
43	DGND		Digital Ground (0V)			
	DGND	- '	The LCD data bus used to transmit data to the LCD module. RED 3 is			
45	R3	0	connected to LCD D2.			
	-		The LCD data bus used to transmit data to the LCD module. RED 4 is			
46	R4	0	connected to LCD_D3.			
			The LCD data bus used to transmit data to the LCD module. RED 5 is			
4-	5.5		connected to LCD_D4. May also be configured as a GPIO pin. See Section			
47	R5	0	5.5.			
			The LCD data bus used to transmit data to the LCD module. Note that G0 is an intensity bit for the LCD display and therefore is tied to the other intensity			
			bits, B0 and R0, which are connected to LCD_D15 on the processor. May			
48	G0		also be configured as a GPIO pin. See Section 5.5.			
			The LCD data bus used to transmit data to the LCD module. GREEN 1 is			
			connected to LCD_D5. May also be configured as a GPIO pin. See Section			
49	G1					
			The LCD data bus used to transmit data to the LCD module. GREEN 2 is			
50	G2		connected to LCD_D6. May also be configured as a GPIO pin. See Section 5.5.			
- 00	02		The LCD data bus used to transmit data to the LCD module. GREEN 3 is			
			connected to LCD_D7. May also be configured as a GPIO pin. See Section			
51	G3		5.5.			
			The LCD data bus used to transmit data to the LCD module. GREEN 4 is			
	0.4		connected to LCD_D8. May also be configured as a GPIO pin. See Section			
52	G4	0	5.5. The LCD data bus used to transmit data to the LCD module. GREEN 5 is			
			connected to LCD D9. May also be configured as a GPIO pin. See Section			
53	G5		5.5.			
			The LCD data bus used to transmit data to the LCD module. Note that B0 is			
			an intensity bit for the LCD display and therefore is tied to the other intensity			
	B0		bits, G0 and R0, which are connected to LCD_D15 on the processor. May			
54	B0					
55	DGND		Digital Ground (0V)			
			The LCD data bus used to transmit data to the LCD module. BLUE 1 is connected to LCD_D10. May also be configured as a GPIO pin. See			
56	B1		Section 5.5.			
			The LCD data bus used to transmit data to the LCD module. BLUE 2 is			
			connected to LCD_D11. May also be configured as a GPIO pin. See			
57	B2		Section 5.5.			
			The LCD data bus used to transmit data to the LCD module. BLUE 3 is			
58	B3		connected to LCD_D12. May also be configured as a GPIO pin. See			
50	DJ	0	Section 5.5.			

		ı			
J1A	Simulation of	.,,	Description		
PIN#	Signal Name	1/0	Description The LCD data bus used to transmit data to the LCD module. BLUE 4 is		
			connected to LCD_D13. May also be configured as a GPIO pin. See		
59	B4	0	Section 5.5.		
- 00		Ŭ	The LCD data bus used to transmit data to the LCD module. BLUE 5 is		
			connected to LCD_D14. May also be configured as a GPIO pin. See		
60	B5	0	Section 5.5.		
			Active low. This signal is the chip/card select for the memory-only CF card.		
			It indicates a word read/write to the card. The CPLD Chip Select Logic		
			decodes this signal. See the LH7A404-11 IO Controller Specification for		
61	CF_nCE	0	further details.		
			This signal is the PC Card ready signal input for a 2nd PCMCIA slot when 2		
60	UB BCC BDVA	١.	devices are used. This signal is pulled up to 3.3V_uP_SDRAM through a 33K resistor.		
62	uP_PCC_RDYA	ı			
			This signal is a general-purpose output. Its standard use is to drive the GPIO LED on the application board (such as the SDK). See the <i>LH7A404</i> -		
63	CPLD_GPIO_1	0	11 IO Controller Specification for further details.		
- 00	01 25_01 10_1	Ŭ	This signal is a general purpose I/O. It is controlled by a memory-mapped		
			address in the CPLD. See the <i>LH7A404-11 IO Controller Specification</i> for		
64	CPLD GPIO 2	I/O	further details.		
			Active low. This signal indicates an Over Current condition for the USB Host		
65	uP_USB2_OVR_CRNT	I	port.		
66	DGND	-	Digital Ground (0V)		
			Active high. This is the data carrier detect signal for the main USB port. It is		
67	uP_USB1_OVR_CRNT		used to determine whether or not the USB interface is currently in use.		
68	uP_USB2_PWR_EN	0	Active high. Enables power supply for USB port 2.		
00	D LIODA DIAID EN		Active Low. Enables power supply for USB port 1. This signal is pulled up to		
69	uP_USB1_PWR_EN		3.3V through a 10K resistor.		
70	uP_USB2_M		USB port 2 data I/O minus. Route as a differential pair with uP_USB2_P.		
71 72	uP_USB2_P uP_USB1_M		USB port 2 data I/O plus. Route as a differential pair with uP_USB2_M. USB port 1 data I/O minus. Route as a differential pair with uP_USB1_P.		
73	uP USB1_W		USB port 1 data I/O plus. Route as a differential pair with uP_USB1_M.		
13	TUP_USB1_F	1/0	Active low. The CPLD Buffer Control Logic decodes this Output Enable		
			signal. This signal controls all five buffers on the LH7A404-11. This signal is		
			pulled up to 3.3V in order to ensure the buffers are tri-stated while powerin		
			on. When the signal is low, the buffers are active. See the <i>LH7A404-11 IO</i>		
			Controller Specification for further details. This signal is pulled up to 3.3V		
74	BUFF_nOE	-	through a 1K resistor.		
75		NC	No internal connection (not implemented on the LH7A404-11)		
			Active high. The CPLD Buffer Control Logic decodes this Buffer Data		
			Direction signal. This signal controls the direction of the data lines through		
			the LH7A404-11's two Data Bus buffers. When low, the data lines are driven		
			out from the processor (write cycle). When high, the data lines are driven in to the processor (read cycle). See the <i>LH7A404-11 IO Controller</i>		
			Specification for further details. This signal is connected to DGND through a		
76	BUFF_DIR_DATA	0	100pF capacitor.		
77	DGND	Ī	Digital Ground (0V)		
			This signal is the microphone input to the AC97 compliant audio codec.		
			Please see the Wolfson #WM9708 AC97 Revision 2.1 Audio Codec		
78	MIC_IN	I	Technical Datasheet for more details.		
			These two pins are used to set the core voltage of the Card Engine. Please		
			reference the ZOOM SDK reference schematics for details on		
79	POWER_SENSE1	0	implementation if the design may require support for different Card Engines.		
			These two pins are used to set the core voltage of the Card Engine. Please		
00	DOWED SENSES		reference the ZOOM SDK reference schematics for details on		
80	POWER_SENSE2	О	implementation if the design may require support for different Card Engines.		

5.3 J1B Expansion Connector Pin Description

	OTB Expansion Connec		2000. p.i.o			
J1B						
Pin #	Signal Name	1/0	Description			
			This is the test clock input for the CPLD JTAG port. It is used for			
			reprogramming the CPLD. This signal is pulled down to DGND through a 10K resistor.			
			Note: If CPLD_JTAG_nOE is driven low, in the field CPLD programming			
			updates are possible.			
1	CPLD TCK	1	Note: Signal shared with LCD controller. Disable LCD to use.			
_			This input transmits data out of the CPLD JTAG port. It is used for			
			reprogramming the CPLD. This signal is pulled up to 3.3V through a			
			resistor.			
			Note: If CPLD_JTAG_nOE is driven low, in the field CPLD programming			
	0010 700	•	updates are possible.			
2	CPLD_TDO	0	Note: Signal shared with LCD controller. Disable LCD to use.			
			This input indicates the mode of CPLD JTAG port. It is used for			
			reprogramming the CPLD. This signal is pulled up to 3.3V through a 10K resistor.			
			Note: If CPLD_JTAG_nOE is driven low, in the field CPLD programming			
			updates are possible.			
3	CPLD TMS	ı	Note: Signal shared with LCD controller. Disable LCD to use.			
	_		This input receives data on the CPLD JTAG port. It is used for			
			reprogramming the CPLD. This signal is pulled up to 3.3V through a 10K			
			resistor.			
			Note: If CPLD_JTAG_nOE is driven low, in the field CPLD programming			
	ODI D. TDI		updates are possible.			
4	CPLD_TDI	ı	Note: Signal shared with LCD controller. Disable LCD to use.			
5	uP_PCC_nOE	0	This signal is PC Card Output Enable, Attribute, and Common Memory space read control.			
	ui _i cc_iice		This signal is for PC Card Enable, Attribute and Common Memory space			
6	uP PCC nWE	0	write control.			
7	uP PCC nIORD		This signal is for PC Card IO Read Output.			
8	uP PCC nIOWR		This signal is for PC Card IO Write Output.			
9	DGND	Ι	Digital Ground (0V)			
			This signal is PC Card Reset Card 1. This signal is pulled up to			
10	uP PCC RESET	0	.			
			This signal is PC Card Enable 1 and is used with PCC nCE2B to decode			
			low and high byte accesses for slot two only. This signal is created in the			
			CPLD (I/O Controller). See the <i>LH7A404-11 IO Controller Specification</i> for			
11	PCC_nCE1B	0	further details.			
			This signal is PC Card Enable 2 and is used with PCC_nCE1B to decode			
			low and high byte accesses for slot two only. This signal is created in the			
12	PCC nCE2B	0	CPLD (I/O Controller). See the <i>LH7A404-11 IO Controller Specification</i> for further details.			
12	1 CC_NCL2B	0	Active low. PCMCIA IOIS16 signal. When low, this specifies that either a			
			16-bit IO card or a write-protected memory-only card is being used. This			
13	uP_PCC_nlOIS16	0	signal is pulled up to 3.3V_uP_SDRAM through a 33K resistor.			
			This is the PC Card ready input for slot one in dual card mode. This signal			
14	uP_PCC_RDYB	ı	is pulled up to 3.3V_uP_SDRAM through a 33K resistor.			
			This is the PC Card wait signal input in dual card mode. This signal is			
15	uP_PCC_nWAIT	ı	pulled up to 3.3V_uP_SDRAM through a 33K resistor.			
			This signal is the Battery Sense 2 input. This value can be read through			
40	D. DOC DVD2		the CPLD Mode Register. See the <i>LH7A404-11 IO Controller Specification</i>			
16	uP_PCC_BVD2	ı	for further details. This signal is pulled up to 3.3V through a 33K resistor.			
			This signal is the Battery Sense 1 input. This value can be read through			
17	uP PCC BVD1	1	the CPLD Mode Register. See the <i>LH7A404-11 IO Controller Specification</i> for further details. This signal is pulled up to 3.3V through a 33K resistor.			
17	GI _I GG_BVD1	- 1	This signal is the Card Detect 2 input. This value can be read through the			
			CPLD Mode Register. See the <i>LH7A404-11 IO Controller Specification</i> for			
18	PCC_nCD2	1	further details. This signal is pulled up to 3.3V through a 33K resistor.			

1/0	Decembries		
	Description This signal is the Card Detect 1 input. This value can be read through the		
	CPLD Mode Register. See the LH7A404-11 IO Controller Specification for		
	further details. This signal is pulled up to 3.3V through a 33K resistor.		
	This signal is for PC Card Register Memory Accesses. May also be		
0	configured as a GPIO pin. See Section 5.5.		
1	Digital Ground (0V)		
	This is a GPIO signal (PA4) that is used to implement the PC Card		
	Voltage Sense 1 signal. May also be configured as a GPIO pin. See		
	Section 5.5. This signal is pulled up to 3.3V through a 33K resistor.		
	This is a GPIO signal (PA5) that is used to implement the PC Card		
	Voltage Sense 2 signal. May also be configured as a GPIO pin. See Section 5.5. This signal is pulled up to 3.3V through a 33K resistor.		
	This is a GPIO signal (PA3) that is used to implement the PC Card Drive		
	signal. May also be configured as a GPIO pin. See Section 5.5. This		
	signal is pulled up to 3.3V through a 33K resistor.		
	This is the PC Card Data Direction signal. May also be configured as a		
0	GPIO pin. See Section 5.5.		
	This signal is connected to UDQM pin on a SDRAM chip to enable		
	uP_D[24:32].		
	This signal is connected to LDQM pin on a SDRAM chip to enable		
	uP_D[16:23].		
	This signal is connected to UDQM pin on a SDRAM chip to enable		
	uP_D[8:15].		
	This signal is connected to LDQM pin on a SDRAM chip to enable uP_D[0:7].		
	This is the IrDA Transmit signal, which is used for the Infrared Mode on		
	UARTC. This signal is pulled up to 3.3V through a 33K resistor.		
	This is the IrDA Receive signal, which is used for the Infrared Mode on		
	UARTC.		
I	Digital Ground (0V)		
	See J1B Jumper Table.		
	See J1B Jumper Table.		
	See J1B Jumper Table.		
	See J1B Jumper Table.		
	See J1B Jumper Table.		
	See J1B Jumper Table.		
	See J1B Jumper Table.		
	See J1B Jumper Table.		
	This is the "Transmit" line for the processor's UART3 interface. See Section 2.9. May also be configured as a GPIO pin. See Section 5.5. This		
	signal is pulled up to 3.3V through a 33K resistor.		
	This is the "Receive" line for the processor's UART3 interface. See		
	Section 2.9. May also be configured as a GPIO pin. See Section 5.5. This		
	signal is pulled up to 3.3V through a 33K resistor.		
	This is the "Clear To Send" line for the processor's UART3 interface. May		
	also be configured as a GPIO pin. See Section 5.5. This signal is pulled		
	Digital Ground (0V)		
	This is a GPIO signal (PE5) that is used to implement the "Ready To		
	Send" line for the processor's UART3 interface. See Section 2.9. May also		
0	<u> </u>		
	This is the "Transmit" line for the processor's UART1 interface. See		
10	Section 2.9. May also be configured as a GPIO pin. See Section 5.5. This is the "Receive" line for the processor's UART1 interface. See		
	Section 2.9. May also be configured as a GPIO pin. See Section 5.5. This		
	signal is pulled up to 3.3V through a 33K resistor.		
	See J1B Jumper Table.		
	See J1B Jumper Table.		

145	I					
J1B Pin #	Signal Name	I/O	Description			
50	MFP11	1/0	Description See J1B Jumper Table.			
51	MFP12		See J1B Jumper Table.			
52	MFP13		See J1B Jumper Table.			
53	MFP14		See J1B Jumper Table.			
54	MFP15					
55	DGND	-	See J1B Jumper Table. Digital Ground (0V)			
56	MFP16	-	See J1B Jumper Table.			
57	MFP17		See J1B Jumper Table.			
58	MFP18		See J1B Jumper Table.			
59	MFP19		See J1B Jumper Table.			
60	MFP20		See J1B Jumper Table.			
61	MFP21		See J1B Jumper Table.			
62	MFP22		See J1B Jumper Table.			
02	IVII I ZZ		This signal is the Smart Battery Clock. May also be configured as a GPIO			
63	MFP23 - uP BMICLK - PB7	0	pin. See Section 5.5.			
- 00	MFP24 - uP BMISW - BMIIO -		This signal is the Smart Battery Single Wire data line. May also be			
64	PB6	0	configured as a GPIO pin. See Section 5.5.			
<u> </u>			This is the Battery Charge signal. This signal is pulled up to 3.3V through			
65	MFP25 - uP nBATCHG	1	a 33K resistor.			
66	DGND		Digital Ground (0V)			
			This is the Battery OK signal. When the board is not plugged into external			
			power, a transition to the run state may not occur unless a valid battery is			
			present and the BATOK signal is high. This signal is pulled up to 3.3V			
67	MFP26 - uP_BATOK	1	through a 33K resistor.			
68	MFP27 - uP_PWM1	0	DC-DC Converter 1 Output (Pulse Width Modulated)			
69	MFP28 - uP_nMCS2	0	Active low. This is the buffered Chip Select 2 signal for off-board use.			
			This signal is the processors SCKE3 signal that is used for accessing			
70	MFP29 – uP_SDCKE	0				
			Active low. This signal is the processor's Synchronous Memory Chip			
71	MFP30 - uP_nSDCS2	0	Select 2.			
			Active low. This signal is the processor's Synchronous Memory Chip			
72	MFP31 - uP_nSDCS1	0	Select 1.			
			Active low. This is the Power Supply signal. When the board is plugged			
			into external power, this signal is asserted and the Card Engine is allow to			
70	MEDOO B EVEDIND		transition to the run state (which also may occur if the battery is in use).			
73	MFP32 - uP_nEXTPWR					
74	MFP33 - uP_BUZZER		This signal is the processor's timer buzzer (254kHz Max) output signal.			
75	MFP34 - MONO_OUT	0	The signal is the main mono output from the AC97 codec.			
76	MFP35 - PC BEEP		This is an analog input to the AC97 codec, typically used for PCBEEP			
			signal.			
77	DGND	ı	Digital Ground (0V) This is an analog input to the AC97 codec, typically used for CD line-in			
78	MFP36 - CD IN L		right signal. Note: This Net is actually connected to CDR of the Codec.			
10	WILL SO - CD_IN_L	-	This is an analog input to the AC97 codec, typically used for CD line-in left			
79	MFP37 - CD IN R	1	signal. Note: This Net is actually connected to CDL of the Codec.			
13		-	This signal is the CD input common mode reference (ground) to the AC97			
80	MFP38 - CD_GND	1	codec.			
	00 0D_014D		10000.			

5.4 J1B Jumper Table

	Jumper				
J1B Pin#	Setting (+/-)	MFP Pin	Signal Name	1/0	Description
33	+		uP KEY COL0		This signal is Column 0 of the keyboard column drivers.
	-		uP BATCNTL	0	This signal is Battery Control for A/D controller battery monitor.
34	+		uP KEY COL1		This signal is Column 1 of the keyboard column drivers.
	-		uP KMICLK	0	This is the Keyboard/Mouse Interface clock signal.
35	+	MFP3	uP_KEY_COL2	0	This signal is Column 2 of the keyboard column drivers.
	-		uP_KMIDAT	0	This is the Keyboard/Mouse Interface data line. This interface implements both PS2 and AT-compatible standards.
36	+	MFP4	uP_KEY_COL3	0	This signal is Column 3 of the keyboard column drivers.
	-		uP_INTBOOT		This is the Internal Boot ROM select signal. This signal is pulled down to DGND through a 10K resistor.
37	+		uP_KEY_COL4		This signal is Column 4 of the keyboard column drivers.
	-		uP_MMC_DATA3		This is the MultiMediaCard Data 2 signal.
38	+		uP_KEY_COL5		This signal is Column 5 of the keyboard column drivers.
	-		uP_MMC_DATA2		This is the MultiMediaCard Data 2 signal.
39	+		uP_KEY_COL6		This signal is Column 6 of the keyboard column drivers.
	-		uP_MMC_DATA1		This is the MultiMediaCard Data 1 signal.
40	+	MFP8	uP_KEY_COL7	0	This signal is Column 7 of the keyboard column drivers.
	-		uP_PWMSYNC	ı	This is the Pulse Width Modulation Synchronizing input signal.
48	+	MFP9	uP_MMC_CMD - SPIDI	I/O	This signal is the MultiMediaCard "Command" signal. This signal is pulled up to 3.3V through a 33K resistor.
	-		uP_CFA8 - CFRESETB - PH1	0	This signal is part of the CompactFlash interface. May also be configured as a GPIO pin. See Section 5.5. This signal is pulled up to 3.3V through a 33K resistor.
49	+	MFP10	uP_MMC_nSELECT - nCS3	0	This signal can either be used as Chip Select 3 or as the MultimediaCard SPI mode chip select.
	-		uP_nCFSTATEN - PH7	0	This is the CompactFlash Status Read Enable signal. May also be configured as a GPIO pin. See Section 5.5.
50	+	MFP11	uP_MMC_DATA0 - SPIDO	0	This is the MultiMediaCard/SPI data 0 signal. This signal is pulled up to 3.3V through a 33K resistor.
					LCD reverse scanning signal (TFT signal). This output
	-		LCD_LBR	0	selects the horizontal scan mode Left Before Right.
51	+	MFP12	uP_MMC_CLK - SPICLK	0	This signal is the MultiMediaCard/SPI clock. This signal has a 22-OHM series resistor.
	-		LCD_UBL	0	LCD reverse scanning signal (TFT signal). This output selects the vertical scan mode Upper Before Lower.
52	+	MFP13	uP_SCI_CLK	0	This signal is the Smart Card Interface clock. This signal has a 22-OHM series resistor.
	-		uP_USB_HN1	I/O	This signal is USB Data Host Negative 1 (Differential Pair). This signal has a 22-OHM series resistor.
53	+	MFP14	uP_SCI_IO	I/O	This is the Smart Card Interface data I/O line. This signal is pulled down to DGND through a 33K resistor.
	-		uP_USB_HP1	I/O	This signal is USB Data Host Positive 1 (Differential Pair). This signal has a 22-OHM series resistor.
54	+	MFP15	uP_MEDCHG	ı	Boot Media Device Change used with the uP_MODE0 and uP_MODE1 signals to specify the boot memory device. In this case, both MODE0 and MODE1 are pulled up and therefore the processor is prepared to boot up from a 32Kbit source on reset. This signal is pulled down to DGND through a 33K resistor.

	Jumper				
J1B	Setting				
Pin#	(+/-)	MFP Pin	Signal Name	I/O	Description
					This is the DMA End of Transfer 0 signal. This signal is
	-		uP_DEOT0	I	pulled down to DGND through a 33K resistor.
					This signal is the Smart Card Detection signal. Upon
					Smart card insertion, this signal is asserted to notify the
					LH7A404 that a new card is preset. May also be configured as a GPIO pin. See Section 5.5. This signal is
56	+	MFP16	uP SCI DETECT - PF5	0	pulled down to DGND through a 33K resistor.
	_		uP_USB_DCP		This signal is the USB device control.
57	+		uP SCI VCCEN		This is the Smart Card Supply Voltage Enable signal
					This signal is the input to channel 8 of the Processor's
	-		uP_A/D5	I	10-bit A/D converter.
58	+	MFP18	uP_SCI_RESET	0	This is the Smart Card Interface reset signal.
					This signal is the input to channel 9 of the Processor's
	-		uP_A/D6	ı	10-bit A/D converter.
					Active low. This signal is the DC-Dc converter pulse width modulator 0 enable. This signal is pulled up to
59	+	MFP19	uP nPWME0	l	3.3V through a 33K resistor.
	_		uP CTCLKIN	İ	This is the Counter Timer Clock input signal.
			- <u>-</u>		This signal is PC Card Enable 2 and is used with
					PCC_nCE2A to decode low and high byte accesses for
					slot one only. This signal is created in the CPLD (I/O
00		MEDOO	DOC OF4.4		Controller). See the LH7A404-11 IO Controller
60	+	MFP20	PCC_nCE1A	U	Specification for further details. This is the "Data Send Ready" line for the processor's
					UART3 interface. See Section 2.9. May also be
					configured as a GPIO pin. See Section 5.5. This signal is
	-		uP_UARTB_DSR	I/O	pulled up to 3.3V through a 33K resistor.
					This signal is the DC-DC converter pulse width
0.4			D DW#40		modulator 0 output. This signal is pulled down to DGND
61	+	MFP21	uP_PWM0	0	through two 33K resistors in parallel.
					This is the "Data Carrier Detect" line for the processor's UART3 interface. See Section 2.9. May also be
					configured as a GPIO pin. See Section 5.5. This signal is
	-		uP_UARTB_DCD - PB4	0	pulled up to 3.3V through a 33K resistor.
					This signal is PC Card Enable 2 and is used with
					PCC_nCE1A to decode low and high byte accesses for
					slot two only. This signal is created in the CPLD. See the LH7A404-11 IO Controller Specification for further
62	+	MFP22	PCC nCE2A	0	details.
				Ť	This is the "Data Carrier Detect" line for the processor's
					UART2 interface. See Section 2.9. This signal is pulled
	-		uP_UARTA_DCD	0	up to 3.3V through a 33K resistor.

5.5 Multiplexed Signal Trade-Offs

Note: Pull Up/Downs are not listed in these tables. Refer to original connector pin description.

5.5.1 J1C Connector SODIMM 144-Pin Multiplexing

J1C Pin #	Signal Name	Alternate Configuration(s)	I/O	Alternate Description(s)
23	uP_IRQD	PF4	I/O	Port F bit 4 GPIO
25	uP_IRQC	PF2	I/O	Port F bit 2 GPIO
27	uP_IRQB	PF1	I/O	Port F bit 1 GPIO
29	uP_IRQA	PF0	I/O	Port F bit 0 GPIO
39	uP UARTA RTS	PC4	I/O	Port C bit 4 GPIO

5.5.2 J1A Expansion Connector Pin Multiplexing

J1A Bin #	Signal Name	Alternate	1/0	Alternate Description(c)
PIN#	Signal Name	Configuration(s)	0	Alternate Description(s)
	100 101410 100 000	LCDSPS		LCD Row Reset (HR-TFT)
1	LCD_VSYNC - LCD_SPS	LCDFP	0	LCD Frame Pulse (STN) (TFT)
		LCDHRLP	0	LCD Horizontal Sync Pulse (HR-TFT)
2	LCD_HSYNC - LCD_HRLP		0	LCD Line Sync Pulse (STN) (TFT)
4	LCD_DON	PC5	1	Port C bit 5 GPIO
5	LCD_MDISP	LCDM	0	LCD AC bias signal (STN)
6	LCD_ VEEEN	PC3	I/O	Port C bit 3 GPIO
		LCDSPS	0	LCD Row Reset (HR-TFT)
11	LCD_VSYNC - LCD_SPS	LCDFP	0	LCD Frame Pulse (STN) (TFT)
		LCDHRLP	0	LCD Horizontal Sync Pulse (HR-TFT)
14	LCD_HSYNC - LCD_HRLP	LCDLP	0	LCD Line Sync Pulse (STN) (TFT)
17	uP_STATUS_1	PE6	I/O	Port E bit 6 GPIO
18	uP STATUS 2	PE7	I/O	Port E bit 7 GPIO
20	uP_AC97_nRESET	PH6	I/O	Port H bit 6 GPIO (If AC97 Codec Not Populated)
41	R0	PD7	I/O	Port D bit 7 GPIO
47	R5	PE0	I/O	Port E bit 0 GPIO
48	G0	PD7	I/O	Port D bit 7 GPIO
49	G1	PE1	I/O	Port E bit 1 GPIO
50	G2	PE2		Port E bit 2 GPIO
51	G3	PE3	I/O	Port E bit 3 GPIO
52	G4	PD0	I/O	Port D bit 0 GPIO
53	G5	PD1	I/O	Port D bit 1 GPIO
54	B0	PD7	I/O	Port D bit 7 GPIO
56	B1	PD2	I/O	Port D bit 2 GPIO
57	B2	PD3	I/O	Port D bit 3 GPIO
58	B3	PD4	I/O	Port D bit 4 GPIO
59	B4	PD5	I/O	Port D bit 5 GPIO
60	B5	PD6	I/O	Port D bit 6 GPIO
62	uP_PCC_RDYA	PF6	I/O	Port F bit 6 GPIO
67	uP_USB1_OVR_CRNT	PC2	I/O	Port C bit 2 GPIO

5.5.3 J1B Expansion Connector Pin Multiplexing

J1B		Alternate		
	Signal Name	Configuration(s)	I/O	Alternate Description(s)
5	uP_PCC_nOE	PG0	I/O	Port G bit 0 GPIO
6	uP_PCC_nWE	PG1	I/O	Port G bit 1 GPIO
7	uP_PCC_nIORD	PG2	I/O	Port G bit 2 GPIO
8	uP_PCC_nIOWR	PG3	I/O	Port G bit 3 GPIO
10	uP_PCC_RESET	PH0	I/O	Port H bit 0 GPIO
13	uP_PCC_nIOIS16	PA2	I/O	Port A bit 2 GPIO
14	uP_PCC_RDYB	PF7	I/O	Port F bit 7 GPIO
20	uP_PCC_nREG	PG4	I/O	Port G bit 4 GPIO
22	uP_PCC_VS1	PA4	I/O	Port A bit 4 GPIO
23	uP_PCC_VS2	PA5	I/O	Port A bit 5 GPIO
24	uP_PCC_nDRV	PA3	I/O	Port A bit 3 GPIO
25	uP_PCC_PCDIR	PG7	I/O	Port G bit 7 GPIO
41	uP_UARTB_TX	PB1	I/O	Port B bit 1 GPIO
42	uP_UARTB_RX	PB2	I/O	Port B bit 2 GPIO
43	uP_UARTB_CTS	PB3	I/O	Port B bit 3 GPIO
45	uP_UARTB_RTS	PE5	I/O	Port E bit 5 GPIO
46	UP_UARTC_TX	PC0	I/O	Port C bit 0 GPIO
47	UP_UARTC_RX	PB0	I/O	Port B bit 0 GPIO
48+	uP_MMC_CMD - SPIDI	SPIDI	I	MMC SPI Mode Data Input
	uP_CFA8 - CFA24 -	PH1	I/O	Port H bit 1 GPIO
48-	CFRESETB - PH1	PCRESET2	0	PC Card reset 2
	uP_MMC_nSELECT -			
49+	nCS3	nCS3	0	Asynchronous memory Chip Select 3
49-	uP_nCFSTATEN - PH7	PH7	I/O	Port H bit 7 GPIO
50+	uP_MMC_DATA0 - SPID0	SPIDO	0	MMC SPI Mode Data Output
51+	uP_MMC_CLK - SPICLK	SPICLK	0	MMC SPI Mode Clock
		PF5	I/O	Port F bit 5 GPIO
56+	uP_SCI_DETECT - PF5	INT5	I	Interrupt 5 input only
60-	UP_UARTB_DSR - PB4	PB5	I/O	Port B bit 5 GPIO
61-	UP_UARTB_DCD - PB4	PB4	I/O	Port B bit 4 GPIO
63	MFP23 - uP_BMICLK - PB7		I/O	Port B bit 7 GPIO
	MFP24 - uP_BMISW -	PB6	I/O	Port B bit 6 GPIO
64	BMIIO - PB6	SMBD	I/O	Smart Battery Data

6 Mechanical Specifications

6.1 Interface Connectors

The LH7A404-11 Card Engine connects to a PCB board through an industry standard 144-pin SODIMM connector (J1C) and two high-density 80-pin connectors (J1A and J1B).

IMPORTANT NOTE: SODIMM Connector must be 3.7mm mating height.

IMPORTANT NOTE: If the product requires safe removal of the Card Engine during the product's lifecycle, the design should allow at least 7.65 mm (0.30") of clearance beyond the Card Engine's back edge (opposite of the SODIMM connector) before placing any baseboard components. This extra space on the baseboard provides room to use an extractor tool to safely remove the Card Engine from the baseboard without flexing the PCB. Please see Logic's White Paper 318 *Card Engine Insertion and Extraction Procedure* for more details.

REF	Manufacturer	Card Engine P/N	Mating Connector P/N
J1A, J1B	Hirose	DF12(3.0)-80DP-0.5V(86)	DF12(3.0)-80DS-0.5V(86)
J1C	Amp	Card Edge	390112-1

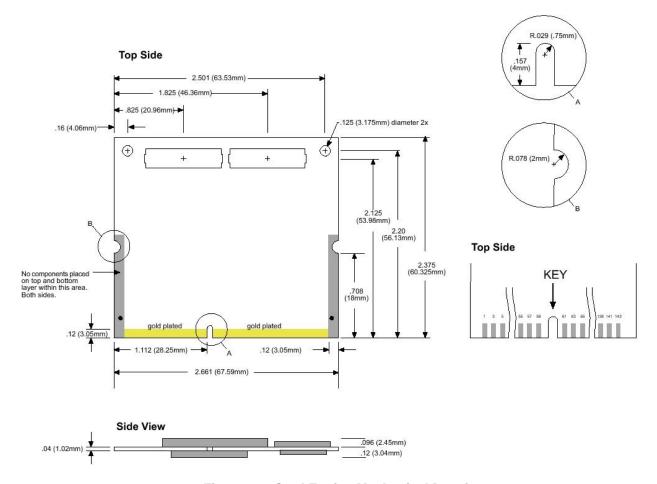
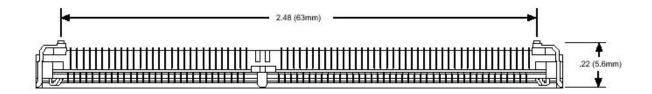
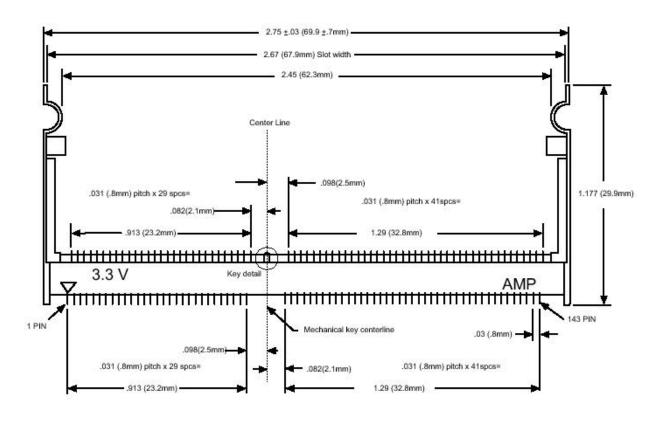


Figure 6.1: Card Engine Mechanical Drawing





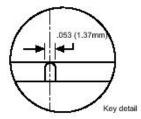


Figure 6.2: SODIMM Connector Specification

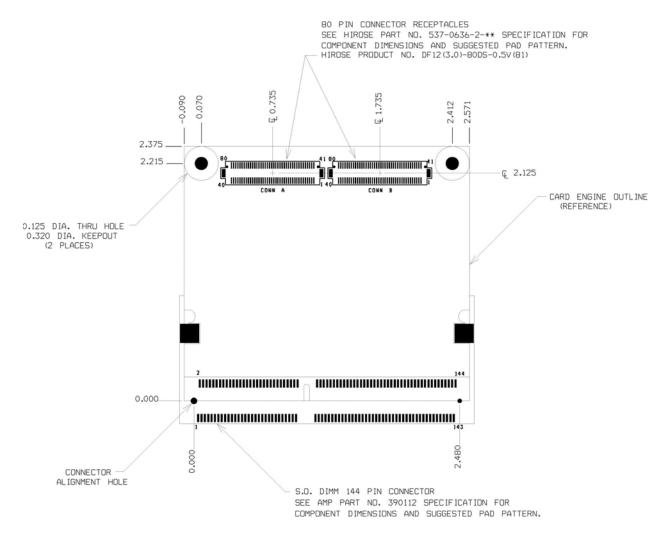


Figure 6.3: Recommended PCB Layout